# SES

Stainless Single-Jet Meter Instructions









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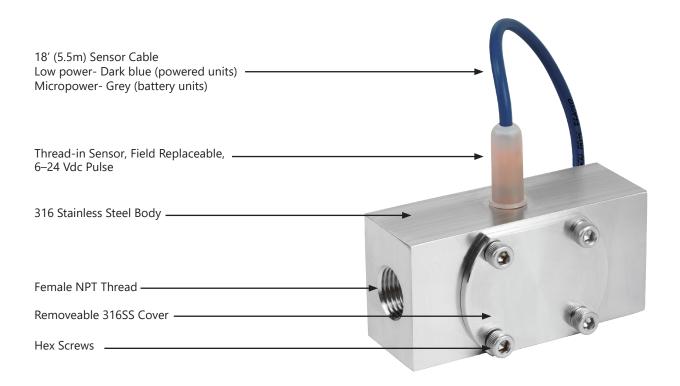
**GENERAL INFORMATION SES INSTRUCTIONS** 

The **SES** single-jet meter provides accurate, wide range The sensor is easily replaced from outside the meter, and flow metering in an extremely rugged stainless steel package. Single-jet simplicity combined with high quality jewel bearings results in long life and relatively high tolerance for problem fluids. Typical applications are chemical batching, proportional chemical injection, fertilizer injection, proportioning of spray chemicals, and general flow rate monitoring.

is compatible with most of the Seametrics indicators and transmitters, as well as most controls and PLC's that accept DC inputs. The standard rotor is PVDF (Kynar®) and the shaft is a special nickel-bonded tungsten carbide.

The optional ceramic shaft increases resistance to some concentrated chemicals. The standard O-ring is Teflon®coated Viton®.

# **Features**



- Jewel Bearings—Ruby Ring and Ball
- Kynar®/Tungsten Carbide Rotor Assembly (Kynar®/Ceramic or Kynar<sup>®</sup>/Silicon Carbide optional)
- Teflon®-coated Viton® O-ring (Viton® or EPDM optional)



Field Replacement of Sensor

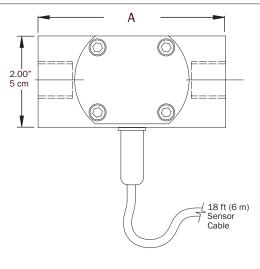
GENERAL INFORMATION SES INSTRUCTIONS

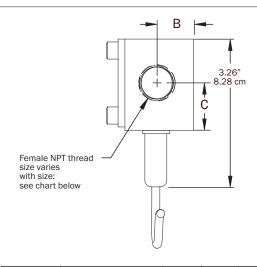
# **Specifications\***

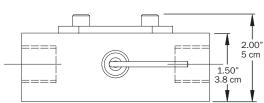
Connection Po	Connection Ports 1/2", 3/4", 1" —Female NPT thread	
Sensor Cable 18 ft (		18 ft (6 m) standard—maximum cable run 2000 ft (607 m)
Materials Body		316 stainless steel
Rotor		PVDF (Kynar*)—2 magnet (6 magnet high resolution optional)
Shaft		Nickel-bonded tungsten carbide (ceramic or silicon carbide optional)
O-Ring		Teflon®-coated Viton® (Viton® or EDPM optional)
Bearings		Ruby ring and ball
	Cover	316 stainless steel
Maximum Temperature		200° F (93° C)
Maximum Pres	ssure	500 psi (35 bar)
Accuracy		±1% of full scale
Power Standard		6–36 Vdc, < 2 mA
	Micropower	3.1–16 Vdc, 60 μA @ 3.6 Vdc (for FT450 and DL76 only)
Outputs Current sinking pulse, 6–24 Vdc		Current sinking pulse, 6–24 Vdc

<sup>\*</sup> Specifications subject to change. Please consult our website for current data (seametrics.com)
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# **Dimensions**







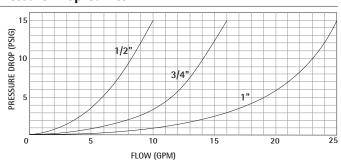
Model	NPT Thread Size	A	В	С
-050	1/2 inch	4.10	0.82	1.04
-075	3/4 inch	4.10	0.82	1.04
-100	1 inch	5.00	0.75	1.00

# **Flow Range**

Model	#	K-Factor* (pulses/gal)	Gal/Min	Liter/Min
-050		535	0.1–10	0.38–38
-075		390	0.2–15	0.75–57
-100		220	0.5–25	1.9–95

\*Nominal K-factors (based on averages) for standard 2-magnet version. High resolution (6-magnet) K-factors are approximately tripled.

# **Pressure Drop Curves**



#### INSTALLATION

# **Piping Requirements**

Standard fittings are female NPT. Straight pipe of at least five diameters upstream of the meter is recommended. Vertical or horizontal installations are acceptable.

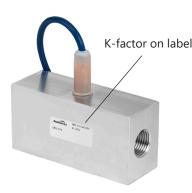


#### WARNING:

This meter has low-friction bearings. DO NOT AT ANY TIME test operation of the meter with compressed air. Doing so will subject it to rotational speeds many times those for which it was designed, and will certainly damage the rotor, shaft, and/or bearings.

#### **K-Factor**

The meter is factory calibrated. The K-factor is found on the label on the meter body and must be input into the control/display for accurate reading.

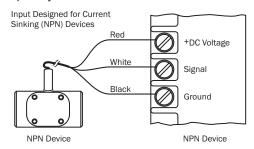


#### CONNECTIONS

# **Connecting to Non-Seametrics Control Devices**

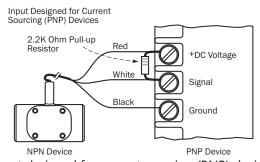
It is often desirable to connect an SES flow sensor to a PLC or industrial computer board, and the sensors are well suited for this. Typically it can be connected directly, or with a single resistor added. The pickup sensors are current sinking (NPN) GMR devices that require 6–36 Volts DC and 2 mA current. They can connect directly to a PLC or computer board if:

- 1. The sensor power supply on the PLC is 6–36 Vdc (24 Vdc is typical).
- 2. The sensor power supply can provide at least 2 mA (100 mA is typical).
- 3. The sensor input on the PLC can accept a current sinking device.
- 4. The PLC frequency response > flow meter output frequency.



Input designed for current sinking devices (NPN)

If the PLC input only accepts current sourcing devices, a pull-up resistor must be added. Typically, on a 24 Vdc input a 2.2 K Ohm resistor will be effective.



Input designed for current sourcing (PNP) devices

Since the three-wire pickup sensors are solid state, they do not exhibit switch bounce and can be used at relatively high frequencies.

If the PLC is equipped with a 4-20 mA analog input module, it is necessary to order the SES flow sensor with some form of 4-20 mA transmitter. Seametrics offers the FT440 indicating transmitter. Follow the connection diagrams for these products to connect to the analog input.

REPAIR SES INSTRUCTIONS

## **Rotor Replacement**

There is only one moving part to this meter. The bearings are made of ruby, which rarely wears out or needs replacement unless they have been physically damaged by severe shock. The shaft is integrally molded into the rotor, and shaft and rotor are replaced as one part. (You may wish to replace the bearings, using the bearing removal tool, while the meter is disassembled for rotor replacement). To replace the rotor, disconnect the meter and remove the four screws that hold the cover in place. Lift the cover and remove the rotor (see parts diagram below).

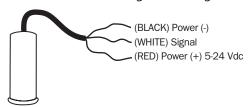
When putting in the new rotor, be sure that the ends of the shaft are in both bearings before tightening the cover. The rotor can be easily dropped into the bottom bearing. Starting the shaft into the upper bearing requires a bit of care. It is easier if the rotor is spinning, which can be done by lightly blowing into a port. When the upper bearing plate drops into place, hold it down and check for free spinning (by blowing lightly) before replacing the cover. Check that the O-ring is in its seat on the bearing plate before replacing the cover. Replace the cover, insert the four cap screws and tighten.

# **Sensor Replacement**

The sensor ordinarily does not need replacement unless it is electrically damaged. If replacement is necessary, unscrew the sensor by hand. Screw the replacement sensor in and tighten by hand.



Reconnect the sensor according to the diagram below.

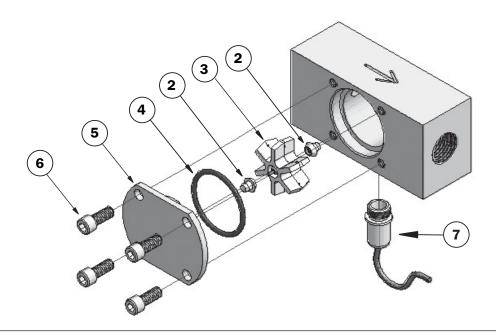


### **SES Parts List**

Cooresponding diagram can be found on the next page, 7.

2	Bearing Assembly (Includes 2)		103313	
	Bearing Removal Tool (not shown)		100372	
3	Rotor Repair Kit			
	Kynar®/Ceramic (2 magnet)		103930	
	Kynar*/Carbide (2 magnet)		103931	
	Kynar*/Silicon Carbide (2 magnet)		103933	
	Kynar*/Ceramic (6 magnet, high res)		100453	
		Kynar*/Carbide (6 magnet, high res)	103932	
		Kynar*/Silicon Carbide (6 magnet, high res)	103934	
4	O-Ring*	EPDM	100264 (optional)	
		Viton®	100219 (optional)	
		Teflon®-coated Viton®	100973 (standard)	
5	Cover	Stainless Steel (SES-050/-075)	100682	
		Stainless Steel (SES-100)	100800	
6	Hexscrew	(4 required)	100693	
7	Sensor	Standard	100419	
		Micropower	100508	

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# **Troubleshooting**

Problem	Probable Cause	Things to Try
No signal after installation	Insufficient flow	Consult Flow Rate Chart Reduce pipe size or use different sensor
	Bad connections to control electronics	Check connections at control: Red (+), Black (-), White (signal)
	Incompatible control	Use 6–36 Vdc power supply - for low power Use 3.1–16 Vdc power supply - for micropowered Add pull up resistor, if using current-sourcing device
	Damaged or missing rotor	Remove flow sensor from fitting and check for free spinning; replace rotor
	Failed magnetic sensor	Replace magnetic sensor
Inaccurate metering	Not enough straight pipe between meter and severe flow disturbance	Move meter away from flow disturbance or field calibrate
	Wrong K-Factory entered	Check fitting for K-Factor, check indicator to see if it is entered properly ("Set K" on FT430, FT440, FT450, or FT520)
	Magnetic sensor failing to pick up each blade	Remove flow sensor from pipe. If indicator is FT430, FT440, FT450, or FT520, set K to 1.00, turn rotor slowly by hand, indicator should cound each blade; replace sensor
	Wrong time units on flow indicator	If using FT430, FT440, or FT520, check left side of display (sec, min, hr, day); change to desired unit

The limited warranty set forth below is given by Seametrics, with respect to Seametrics brand products purchased in the United States of America.

Seametrics warrants that products manufactured by Seametrics, when delivered to you in new condition in their original containers and properly installed, shall be free from defects in material and workmanship. Seametrics products are warranted against defects for a minimum period of two (2) years from date of installation, unless otherwise specified, with proof of install date. If no proof of install date can be provided, warranty period will be two (2) years from date of shipment from Seametrics, as defined on Seametrics' invoice. Seametrics' obligation under this warranty shall be limited to replacing or repairing the part or parts, or, at Seametrics' option, the products, which prove defective in material or workmanship. The following are the terms of Seametrics' limited warranty:

- a. Buyer must give Seametrics prompt notice of any defect or failure and satisfactory proof thereof.
- b. Any defective part or parts must be returned to Seametrics' factory or to an authorized service center for inspection.
- c. Buyer will prepay all freight charges to return any products to Seametrics' factory, or another repair facility. as designated by Seametrics.
- d. Defective products, or parts thereof, which are returned to Seametrics and proved to be defective upon inspection, will be repaired to factory specifications.
- e. Seametrics will deliver repaired products or replacements for defective products to the buyer (ground freight prepaid) to the destination provided in the original order.
- f. Products returned to Seametrics for which Seametrics provides replacement under this warranty shall become the property of Seametrics.
- g. This limited warranty covers all defects encountered in normal use of Seametrics products, and does not apply to the following cases:
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  - ii. Failure to follow operating, maintenance, or environmental instructions prescribed in Seametrics' instruction manual
  - iii. Products not used for their intended purpose
  - iv. Alterations to the product, purposeful or accidental
  - v. Electrical current fluctuations
  - vi. Corrosion due to aggressive materials not approved for your specific product
  - vii. Mishandling, or misapplication of Seametrics products
  - viii. Products or parts that are typically consumed during normal operation
  - ix. Use of parts or supplies (other than those sold by Seametrics) which cause damage to the products, or cause abnormally frequent service calls or service problems
- h. A new warranty period will be established for repaired products, or products replaced during the original warranty period.
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