

Stationary area velocity flow meter for partially filled pipes or pressurized pipes and open channels





Area Velocity Sensor



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1. GENERAL INFORMATION

This user manual provides all necessary information for the operation and the efficient and safe use of the **IS-6000 Doppler** flow meter. It contains important information on product identification, storage, installation, commissioning, operation, maintenance and disposal of the device. Before putting the device into operation, read this user manual carefully. To prevent possible injuries to the user and damage, use the device only for the intended use described below. Always keep this document handy in the vicinity of the device! If you do not understand the contents of this document, contact the manufacturer. In no case may the manufacturer be held reliable for any damage or injury caused by misunderstanding of the information.

1.1. Copyright

All rights reserved. The contents and works in this document are subject to German copyright. Contributions from third parties are identified as such. No part of this documentation may be reproduced in any form, stored or transferred, neither electronically, mechanically, photo-technically, by recording on data media or otherwise, as long as no expressly written authorization from the publisher is present.

1.2. Data Protection and Security

All data should be backed-up prior to the installation of any peripheral storage device. The manufacturer will not be responsible for any loss of data resulting from the use or misuse of this or any other product from the manufacturer. Data security is given by personated login with username and password. Data will be saved on the server with appropriate security measures for protection against data loss, data abuse and unauthorized data modifications.

There are inherent security risks in transmitting data via the internet. It is not possible to safeguard completely against unauthorized access by third parties.

The use of contact data published within the framework of the imprint obligation by third parties for the transmission of not expressly requested advertising and information material is hereby expressly rejected.

1.3. Liability

In case of inappropriate or unintended use, no liability for the proper function of the device can be assumed. Improper installation and operation of the device will void the warranty. The manufacturer has made every effort to assure the accuracy of the contents of this manual and the software. However, the manufacturer can offer no guarantee that the information provided is accurate and/or free of error. The information provided in this manual is subject to change without notice at any time. The manufacturer reserves the right to alter designs, layouts or software without prior notification and will not be liable in any way for possible consequences of such changes.

1.4. EU Conformity Declaration

The manufacturer hereby declares that this product complies with Directive 2014/30/EU, 2014/35/EU, 014/53/EU, 2014/65/EU.

1.5. Warnings and Safety Symbols

Depending on the hazard level, warnings are displayed as follows.

▲ DANGER	Immediate danger. Indicates a potentially or imminently hazardous situation which, if not avoided, will result in death or serious injury.
AWARNING	Medium risk. Indicates a potentially or imminently hazardous situation which, if not avoided, <i>could</i> result in death or serious injury.
ACAUTION	Minor risk. Indicates a potentially hazardous situation that <i>may</i> result in minor or moderate injury or damage.

IMPORTANT

Important handling instruction. Indicates a situation which, if not avoided, may cause damage to the device. Information that requires special emphasis.

NOTE: This symbol indicates helpful notes and information for handling the device.

2. GENERAL SAFETY INSTRUCTIONS

2.1. Requirements for Personnel

Installation, electrical connections, commissioning, operation, and maintenance of the device must be carried out by qualified, specially trained and authorized personnel.

Personal injuries and serious damage to the device are caused by insufficiently qualified personnel.

Qualified personnel:

- Are persons who, through their professional training and education, are familiar with the safety guidelines of electrical and automation engineering.
- Are persons who, as project, commissioning, and installation personnel, are authorized to commission, ground and label circuits and devices/systems in accordance with the standards of safety engineering.
- Must be able to safely assess the results of their work and must be familiar with the contents of these
 operating instructions.

Special trained personnel:

Are persons, for example fitters or electricians, who can perform various tasks such as transport, assembly and installation
of the product under the supervision of an authorized person. The persons must have experience in handling the product.

Authorized personnel:

 Are persons who are indented to work on the basis of legal regulations or have been approved by the manufacturer for certain activities.

The following requirements must be met:

- The user manual must be read carefully and fully understood by qualified personnel. Instructions must be followed.
- Qualified personnel must be trained and authorized by the plant operator.
- During work on and with the device, the required personal protective equipment must always be worn.
- All applicable national standards, safety requirements and accident prevention regulation have to be observed.

2.2. Intended Use

AWARNING

IMPROPER USE CAN SERIOUSLY COMPROMISE THE SAFETY OF THE DEVICE. THE DEVICE IS EXCLUSIVELY DESIGNED TO BE USED FOR PURPOSES AS DESCRIBED BELOW.

KEEP WITHIN THE SPECIFIED PRESSURE AND TEMPERATURE RANGE WHILE USING THE DEVICE.

RESISTANCE OF ALL FLUID-WETTED PARTS OF THE DEVICE AGAINST THE MEASURED FLUID MUST BE MADE SURE IN ORDER TO AVOID CORROSION AND ABRASION.

NOTE: The manufacturer is not liable for any damage resulting from improper use or use for other than the intended purpose.

The IS-6000 Doppler stationary pulse-Doppler System is a permanent velocity area flow meter that measures flow in full and partially full pipes with 4...80 in. (100...2000 mm) in diameter, and in open channels with water depths from 1.5...80 in. (0.04...2 m).

2.3. Workplace Safety

During work on and with the device the required personal protective equipment must always be worn. All applicable national standards, safety requirements and accident prevention regulation must be observed.

2.4. Operational Safety

Operate the device in proper technical condition and fail-safe condition only. The operator is responsible for interference-free operation of the device.

2.5. Product Safety

This measuring device is designed in accordance with good engineering practice to meet state-of-the-art safety requirements. It has been tested and left the factory in a condition in which it is safe to operate. It meets general safety standards and legal requirements. It also complies with the EU directives listed in the device-specific EU Declaration of Conformity.

2.6. Electrical Safety

AWARNING

DISCONNECT DEVICE

SINCE THE DEVICE CANNOT BE SWITCHED OFF AT THE HOUSING, IT IS ABSOLUTELY NECESSARY TO CONNECT THE SYSTEM TO AN EXTERNAL DISCONNECTING DEVICE.

AWARNING

DANGEROUS CONTACT VOLTAGES

- THE FUNCTIONAL EARTHING IS NOT IDENTICAL TO THE PROTECTIVE EARTHING ACCORDING TO DIN VDE 0100!
- EMC GROUND CONNECTORS ONLY FULFIL SECONDARY MEASURES FOR PROTECTION AGAINST DANGEROUS CONTACT VOLTAGES.
- THE GREEN-YELLOW WIRES OF THE PROTECTIVE CONDUCTOR (PE) FULFIL THE MEASURES FOR PROTECTION
 AGAINST DANGEROUS CONTACT VOLTAGES, BUT NOT THE REQUIREMENTS OF EMC DIRECTIVE 2014/30/EU.
- WHEN EARTHING A SYSTEM, TAKE APPROPRIATE PROTECTIVE AND FUNCTIONAL MEASURES IN ACCORDANCE WITH DIN VDE 0100 AND EMC DIRECTIVE 2014/30/EU.

AWARNING

PROTECTIVE GROUNDING

SUITABLE MEASURES FOR ERROR PROTECTION MUST BE CARRIED OUT. THE CONDUCTIVE SYSTEM PARTS TO BE PROTECTED MUST BE CONNECTED TO A SUITABLE EARTHING CONDUCTOR VIA THE PE CONDUCTOR, SO THAT THE SYSTEM PARTS WITH A FAULT ARE SWITCHED OFF BY OVERCURRENT PROTECTION DEVICES.

Symbols	Description
	Protective conductor connection
(+)	This symbol refers to the protective conductor connection of the device.
	Depending on the type of installation, the device may only be operated with a suitable protective conductor connection in accordance with the applicable laws and regulations
L	Phase conductor
N	Neutral conductor

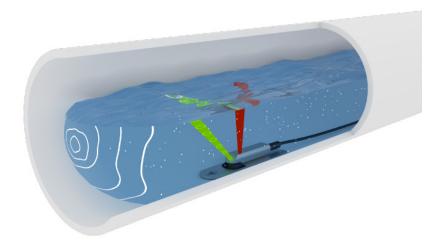
3. PRODUCT DESCRIPTION

The IS-6000 Doppler stationary ultrasonic flow meter continuously measures the flow of water and wastewater in pressurized and partially filled pipes and in open channels with water depths from 1.5...80 in. (0.04...2 m).

As a standard, the flow meter consists of a transmitter and an ultrasonic area velocity sensor for combined velocity and water level measurement (*see Figure 1*). Discharge is then calculated by multiplication of the average flow velocity and the wetted cross-sectional area. The transmitter allows connection of up to 3 ultrasonic area velocity sensors for simultaneous measurement at up to 3 different measurement spots in one cross-section.

Alternatively, additional external water level sensors (for example, a hydrostatic level sensor or an ultrasonic down-looking level sensor) can be connected to the system depending on specific site conditions, providing accurate water level measurement in case of water level fluctuations.

For discharge measurement in pressurized and partially filled pipes, insertion sensors are used. Insertion sensors are installed into the existing pipe work through ball valves allowing the installation and removal of the entire sensor for repair, replacement, or cleaning without dewatering the pipe.



 $Figure \ 1: \ Combined \ ultrasonic \ velocity \ and \ water \ level \ measurement \ with \ an \ area \ velocity \ sensor \ (combination \ sensor)$

The IS-6000 Doppler transmitter incorporates all the required algorithms and software for measurement accuracy and repeatability. Parameterization of the measurement site, data logging, visualization and data transfer is possible by using the browser-based control and management user interface, which can be run in any standard web browser via PC, notebook, tablet or smart phone, regardless of location, time and operating system.

Applications:

Based on the pulsed wave Doppler principle, the flow measurement of IS-6000 Doppler meter requires suspended particles or gas bubbles in the flowing liquid as reflectors of the acoustic signals. Therefore, the meter is ideally suited for continuous flow monitoring in slightly to heavily polluted media.

- Wastewater treatment plants (influent measurement, real-time process control, effluent measurement)
- Wastewater collection systems (infiltration studies, hydraulic model calibration, event notification, long term trend analysis)
- Urban drainage

3.1. Scope of Delivery

IMPORTANT

Check the packaging and the contents for damage. Check that delivery is complete and agrees with the shipping documents and your order. If damages occurred or any items are missing, please contact the manufacturer.

The scope of delivery

- IS-6000 Doppler transmitter
- Area velocity sensor or insertion sensor including cable
- User manual

Optional Accessories

- · External hydrostatic level sensor or external ultrasonic level sensor
- Integrated LTE/HSPA+/GPRS (4G/3G/2G) modem incl. 4G/LTE dipole antenna
- Mounting systems (sensor mounting plates, in-pipe tension rings, scissors rings)

3.2. Storage

Store the equipment in a dry and dust-free place. Avoid durable exposure to direct sunlight. Store the device ideally in its original packaging. Storage temperature: -4...158° F (-20...70° C), ideally 68° F(20° C).

3.3. Nameplate

NOTE: Check the device nameplate to make sure that the device is delivered according to your order.

The nameplate (see Figure 2) indicates important data for identification and use of the measuring system.



- 1 Manufacturer name
- 2 Product name
- 3 Serial number transmitter (S/N)
- 4 Power supply data
- 5 Ambient temperature range
- 6 Manufacturing date mm/yyyy
- 7 Network number
- 8 IP protection class
- 9 CE mark

Figure 2: Nameplate (example)

3.4. Measuring System

3.4.1. Transmitter

The transmitter (see Figure 3 on page 12) is designed to operate ultrasonic velocity sensors and to calculate the flow rate. The flow computer incorporates all of the required algorithms and software to ensure accuracy and repeatability of the measurements. The IP66 (NEMA 4) compact flow display computer has a 4 lines \times 20 characters alphanumeric LC display and a 4-button keypad. All configuration data, measurement data, and calculated data are stored on a 16GB Micro-SD card. It controls the measurements, calculates the flow rate and provides freely programmable current outputs, status alarm, frequency outputs and totalizer readings.

NOTE: For use and installation of IS-6000 Doppler meter in potentially explosive atmospheres, the transmitter is connected to an explosion-proofed stationary Ex-flow rate module (according to ATEX Directive 2014/34/EU). The Ex-flow rate module comes with an area velocity sensor with an explosion-proof connection cable. For detailed description of the Ex-flow rate module and the connection to the IS-6000 Doppler transmitter, an additional user manual is provided by the manufacturer.

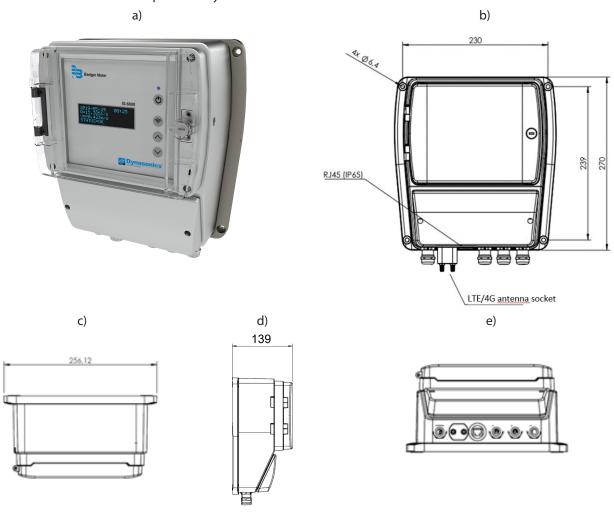


Figure 3: a),b) Front view of transmitter housing for wall installation, enclosure dimensions (in mm) c),d) top view and side view, dimensions (in mm) e) bottom view

3.4.2. Software

The IS-6000 Doppler flow meter is programmed and operated by a browser-based user interface that simply can be run via WiFi or LAN connection in any standard web browser via PC, notebook, tablet or smart phone, regardless of location, time and operating system.

The graphical user interface is menu-driven for rapid commissioning, easy parameterization of the measurement site and data visualization and management.

Main features are:

- Intuitive menu-driven user interface
- · Direct communication (WiFi) with measuring system
- Automatic identification of measuring system via system-specific IP address
- · Status information of measuring system, alarm functions
- Simple parameterization and commissioning of measuring system
- Flexible graphical data visualization (for example real-time zoomable data and time series, data history, velocity profiles)
- Data logging of incoming data and easy data transfer
- Remote system diagnostics, service and maintenance
- · Protection from unauthorized access through individual access authorization

3.4.2.1. System requirements

- Network connection (WiFi, LAN)
- Standard latest web browser, for example: Internet Explorer, Firefox, Chrome, Safari, Opera, Android Browser.

3.4.3. Sensors

As a standard, the IS-6000 Doppler meter comes with an area velocity sensor for ultrasonic flow velocity and water level measurement. Depending on the measurement task and site conditions external sensors for example for water level measurement such as a pressure sensor or a non-contact ultrasonic level sensor can be connected via 4...20 mA interfaces.

3.4.3.1. Area Velocity Sensors

The mouse-type area velocity sensor measures flow velocity and water level based on the pulse (echo) coherent method corrected by an embedded temperature sensor. The small sensor dimensions mean less interference resulting in more accurate velocity measurements, especially under low flow conditions.

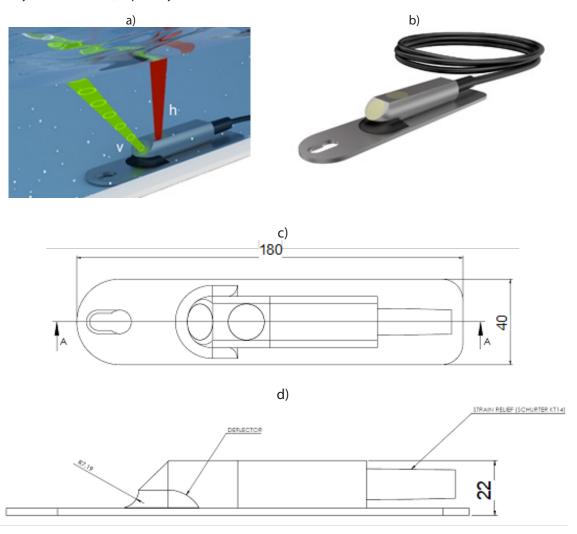


Figure 4: a) Scheme for combined ultrasonic velocity (v) and water level (h) measurement b) Area velocity sensor incl. mounting plate c) Dimensions (length, depth in mm), top view d) Dimensions (height in mm), side view

3.4.4. Sensor Mounting Systems

All sensors can be attached to a mounting plate, spring or scissors rings. The sensor is first attached to a carrier to be slid onto any of the compatible mounting systems. This maintains a height suitable for measuring flow rates and velocities at very low water levels. To install the sensors in rectangular, trapezoidal or earthen channels, use the sensor mounting plate. Stainless steel spring rings simplify sensor installation in cylindrical pipes. Six standard diameter sizes from 8...24 in. (200...600 mm) are available. Before entering the manhole, the sensor and the cable can be fastened in place to the downstream edge of the ring. The self-expanding device sits tight by expanding the band for a friction fit inside the pipe. The adjustable scissors ring is installed in large diameter pipes from 20...57 in. (500...1450 mm). It consists of a base section and one or more pairs of extensions to fit the size of the pipe and a scissors mechanism.



- ① Pipe
- ② Tension ring with pre-drilled holes to fasten sensor cable to the ring
- ③ Area velocity sensor on sensor mounting plate

Figure 5: Example for sensor mounting system (tension ring) in a pipe

4. INSTALLATION

IMPORTANT

Be advised that possible mounting and connection errors and their effects are beyond our control. Therefore, the manufacturer cannot be held responsible for damages as a result of incorrect handling, installation and maintenance of the equipment.

4.1. Installation Location

For reliable, continuous stability and accuracy of the device, follow the instructions below:

- Choose a measuring site with a steady distribution of flow velocity over the cross-section, avoiding highly turbulent flow conditions.
- Avoid measuring sites with sediment accumulation or deposits.
- Always observe ambient temperature at the installation site. Avoid exposure to heat, frost, extreme temperature fluctuations and direct sunlight.
- Make sure that the device is protected from mechanical impacts and vibration.
- If using the device under corrosive or aggressive atmospheric conditions, make sure the location is well ventilated.
- Protect the transmitter from flooding.

4.2. Mounting the Transmitter

NOTE: Mount the transmitter in a position that is protected against direct sunlight and rainfall.

- 1. Select a proper position on a flat wall surface. Make sure to have a sufficient power supply in the vicinity of the transmitter. Make sure the cabling is safe.
- 2. Mark the upper drill hole at the positions of the upper hanger in the middle on top of the transmitter enclosure.
- 3. Drill a hole for corresponding wall plug for fixing screw at the marked point.
- 4. Mount the transmitter with fixing screw on the wall. Use suitable screws and plugs depending on the wall construction and installation conditions. Make sure the enclosure is aligned horizontally.
- 5. Then mark the holes for the last two drillings on the left and right site on the bottom of the enclosure and follow the procedure described above.
- 6. Be sure to tighten the screws firmly.

Temperature Strip

For monitoring ambient temperatures higher than 104° F (40° C), view the yellow self-adhesive temperature strip inside the transmitter enclosure.

An increase in temperature in the range of 104...160° F (40...71° C) will cause an irreversible change of color of the specific segment from light grey to dark grey. The dark color will remain even after subsequent cooling, indicating the maximum temperature that has been reached.

Indicated temperature segments: 104° F (40° C), 109.4° F (43° C), 114.8° F (46° C), 120.2° F (49° C), 129.2° F (54° C), 140° F (60° C), 150.8° F (66° C), 159.8° F (71° C).

NOTE: Always check temperature strip when opening the enclosure.

The temperature strip is for quality assurance and warranty demands. Removal of the strip invalidates the warranty.

4.3. Mounting the Sensors

ACAUTION

SENSORS IN USE MUST BE PROTECTED FROM MECHANICAL DAMAGE DUE TO IMPACTS OR ABRASION (FOR EXAMPLE FROM COARSE SEDIMENT LOAD OR ABRASIVE SEDIMENT MATERIAL).

Special mounting systems are available to make sensor installation easier and reduce installation time. Sensors are first mounted to carriers that can be easily attached to any of the compatible mounting system. The signal cable is already fixed at the sensor. The cable length has to be adapted to site conditions.

Always make sure that sensor cables connected to the transmitter are mounted firmly to the wall as tripping on the cables can cause both serious personal injury and permanent damage to cables and connectors. Check again, that the measuring window is not affected by the cables.

ACAUTION

ANY ADJUSTMENTS OF CABLE LENGTHS MUST BE CARRIED OUT SOLELY BY THE MANUFACTURER. PLEASE CONTACT OUR SERVICE TECHNICIANS.

4.3.1. Installating an Area Velocity Sensor

Normally, flow velocity is measured against the flow direction due to possible turbulences caused by the sensor itself and the cable that might affect the measurement.

However, the sensor measures flow velocity regardless of the flow direction (*see Figure 6*). Readings measured with sensors installed against the flow direction are registered as positive values (+v) and vice versa (-v).



Figure 6: Installation of sensors against flow direction (1) and in flow direction (2)

4.4. Calibration

For all flow velocity measuring systems for partially filled cross-sections that are installed in existing pipelines, a calibration of the measuring site (measurement of network, tracer measurement) is recommended in order to receive an optimum measuring accuracy. During calibration, the water level at the measuring site should be at least 4 in. (10 cm). For instructions for calibration of measuring sites, see DIN EN ISO 748 [2].

NOTE: The calculation for calibration is performed via software in the calibration menu of user interface (▶ Parameter ▷ Calibration).

5. ELECTRICAL CONNECTION

AWARNING

- Improper connection can cause injury or death. The electrical connection must be carried out by a certified electrician.
- Observe the national regulations for electrical installations! By handling products that are supplied by electrical voltage, you must observe the valid IEC instructions, especially IEC 60364, IEC 61558, IEC 60335, IEC 60598-1 and IEC 60065.
- Before opening an instrument, pull off the main plug and make sure that the instrument is without power supply.
 Parts, construction groups or instruments must only be set into operation if they are built into a housing and
 protected against touching. During installation they must be without power. Only use tools at the instruments, parts
 or construction groups the devices are disconnected from the supply voltage and the electric loads stored in the
 construction groups inside the instrument are unloaded. Conducting cables or conductors that are connected to the
 instrument, part or construction group must be checked continuously for isolation faults or sites of fractures. If a fault
 is found in the supply line, the instrument must be switched off immediately until the defective line has been replaced.
- By using construction elements or groups please make sure that the features for electrical sizes are observed according
 to the respective description. In case it is not possible to clarify clearly for a non-commercial end-user which electrical
 variables are valid for a part or a construction group, how external wiring is to be undertaken, which external
 components or additional devices can be connected and which connection values these external components may
 have, always contact an expert for respective information.
- Before operation, generally check if the instrument or construction group is suitable for the field of application. If there
 is any doubt, you must confer with a technical expert or the manufacturer of the used construction group.
- Compare specifications on the nameplate and check for the correct supply voltage on the nameplate.
- Feed the power supply cable and signal cables through the appropriate cable entries.

5.1. Terminal Compartment

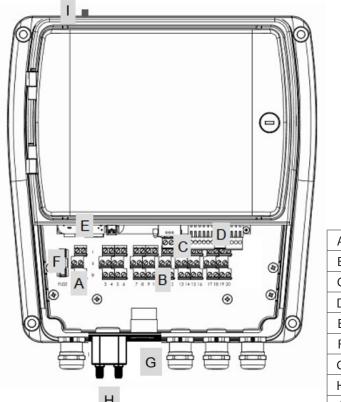
AWARNING

RISK OF ELECTRIC SHOCK! SWITCH OFF POWER SUPPLY BEFORE OPENING THE DEVICE. DO NOT INSTALL OR WIRE THE DEVICE WHILE IT IS CONNECTED TO THE POWER SUPPLY. DISREGARDING COMPLIANCE WITH THIS PRECAUTION MAY RESULT IN IRREPARABLE DAMAGE TO THE ELECTRONICS.

IMPORTANT

- **Protective grounding:** Suitable measures for error protection must be carried out. The conductive system parts to be protected must be connected to a suitable earthing conductor via the PE conductor, so that the system parts with a fault are switched off by overcurrent protection devices
- **Electronic Discharge:** Electronic components can be destroyed by electrostatic discharge during in-stallation. Avoid high electrostatic charges by using suitable grounding measures.
- Disconnecting device: The device must be connected and disconnected to the mains by means of a disconnecting device.
- **Power / connection cable:** Upon delivery, the transmitter power cable is already connected. If necessary, use a strain relief for the connected cable to prevent accidental disconnection.
- The system has no on / off switch. It is therefore imperative to attach the system to an additional circuit breaker (at least 2A) to disconnect the system from the power supply in the event of a fault or repair. The circuit breaker should be within easy reach.
- It is necessary to connect the system to an external overvoltage protection device (for example, a circuit breaker).

The terminal configurations have been set by the manufacturer depending on the specifications ordered. For individual wiring of additional components, see "5.1.1. Pin Assignments" on page 20. To open the terminal compartment, unscrew the enclosure cover.



Α	Power supply (AC/DC)
В	Connectors I/Os, relay outputs
С	Sensor connection block
D	MODBUS (RS-485, RS-232)
Е	LAN, RJ45, SIM Card
F	Fuse
G	Cable entries blocks
Н	LTE/4G antenna socket
I	WiFi antenna socket

Figure 7: Overview terminal compartment

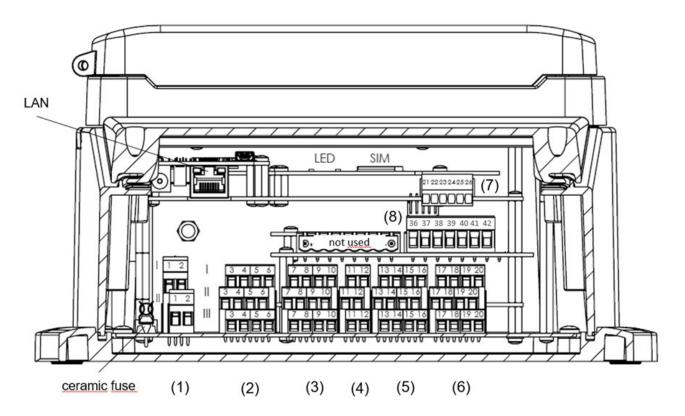
NOTE: The 4G/LTE dipole antenna is connected via the antenna connector on the enclosure bottom next to the cable entry blocks.

IMPORTANT

Specification for cables for wiring:

- Use copper cable only
- Temperature: min. 158° F (70° C)
- Cable diameter: 0.04 in.² (1 mm²⁾

5.1.1. Pin Assignments



- (1) Pins # 1-2 Power supply (AC / DC)
- (2) Pins # 3-6 Relays outputs
- (3) Pins # 7-10 Digital inputs /outputs
- (4) Pins # 11-12 Service interface (RS-485)
- (5) Pins # 13-16 Analog outputs
- (6) Pins # 17-20 Analog inputs (e.g. for connection of level sensor)
- (7) Pins # 21-26 MODBUS (RS-485, RS-232)
- (8) Pins # 36-42 Connector block area velocity sensor

NOTE: Upon delivery, the enclosure cover is grounded with a green-yellow grounding cable.

Figure 8: Overview pin assignment

Block	No. (row) (no.)	Name	Description	Cable Color
(1) AC Power Supply	(I) (1)	L Phase*	Power supply	Brown or Black
(100240V AC)	(II) (1)	PE	Protective earth; grounding terminal	Green/Yellow
(I) (2		N Neutral*	Power supply	Blue
	(II) (2)	PE	Protective earth; grounding terminal	Green/Yellow
(1) DC Power Supply	(I) (1)	+ DC In	Power supply	Red
(936V DC)	936V DC) (II) (1) PE Protective earth; grounding terminal		Green/Yellow	
	(I) (2)	- DC In	Power supply	Black
	(II) (2)	PE	Protective earth; grounding terminal	Green/Yellow

* L = external conductor, N = neutral conductor

(1) (2) AC/DC Relay (1) (3) (3) (3) (3) (4) (Block	No. (row) (no.)	Name	Description
(ii) (ii) COM1 normally closed (NC) or normally open (NO) contact available max. 40V / 1 A AC, max. 60V / 1 A DC (ii) (4) NO2 Relay 2 normally closed (NC) or normally open (NO) contact available max. 40V / 1 A AC, max. 60V / 1 A DC (ii) (5) NO3 Relay 3 normally closed (NC) or normally open (NO) contact available max. 40V / 1 A AC, max. 60V / 1 A DC (ii) (5) NO3 Relay 3 normally closed (NC) or normally open (NO) contact available max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (6) NO4 Relay 4 normally closed (NC) or normally open (NO) contact available max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (6) NO4 normally closed (NC) or normally open (NO) contact available max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (7) +DO1 pulse output 1 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (7) +DO2 pulse output 1 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) pulse width / frequency adjustable max. 40V / 1 A AC, max. 60V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) pulse width / frequency adjustable max. 40V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) max. 30V max. 40V / 1 A DC (iii) (8) +DO2 pulse output 2 (+) max. 30V max. 40V / 1 A DC (iii) (9) +DI1 digital input 1 (+) max. 30V max. 40V / 1 A DC (iii) (10) +DO2 digital input	(2) AC/DC Relay		NO1	Relay 1
(III) 3	-			·
(III) (4) COM2 normally closed (NC) or normally open (NO) contact available max. 40V / 1A AC, max. 60V / 1A DC		(III) (3)	NC1	max. 40V / 1A AC, max. 60V / 1A DC
(III) (4) NC2 max. 40V / 1A AC, max. 60V / 1A DC		(I) (4)	NO2	Relay 2
(1) (5) NO3 Relay 3		(II) (4)		normally closed (NC) or normally open (NO) contact available
(III) (5) COM3 normally lopen (NO) contact available max. 40V / 1 A AC, max. 60V / 1 A DC				
(III) (5) NC3 Max. 40V / 1A AC, max. 60V / 1A DC		1		
(I) (6) NO4 Relay 4 (III) (6) COM4 normally closed (NC) or normally open (NO) contact available (III) (6) NC4 max. 40V / 1A AC, max. 60V / 1A DC (III) (7) + DO1 (III) (7) + 24V DC* (III) (8) + DO2 (III) (8) + DO2 (III) (8) - DO2 (III) (8) - DO2 (III) (8) - DO2 (III) (9) + D11 (III) (9) + D11 (III) (10) + D12 (III) (10) + D12 (III) (10) - D12 (III) (10) GND (III) (10) GND (III) (11) A not connected (III) (11) A not connected (III) (12) Z not connected (III) (12) Z not connected (III) (12) Z not connected (III) (12) Anot connected (III) (12) Anot connected (III) (12) Anot connected (III) (13) + AO1 (III) (13) + AO2 (III) (14) GND (III) (15) - AO3 (III) (16) - AO4 (III) (17) - A1 (III) (17) - A1 (III) (18) GND (III) (19) - AI3 (III) (19) - AI4 (I		l .		
(II) (6) COM4 normally closed (NC) or normally open (NO) contact available (III) (6) NC4 max. 40V / 1A AC, max. 60V / 1A DC max. 60V / 1A DC (III) (7) +20 DT pulse output 1 (+) pulse width / frequency adjustable pulse output 1 (+) pulse width / frequency adjustable pulse output 2 (+) output 2 (+) pulse width / frequency adjustable pulse output 2 (+) output adjustable pulse output 2 (+) output adjustable pulse output 2 (+) output adjustable pulse output 2 (+) ana. 30V (iii) (10) output 2 (+) ana. 30V (iii) (10) output 2 (+) ana. 30V (iii) (11) output 2 (+) ana. 30V (iii) (11) output 3 (+) analog output 3 (+) active, 420 mA, load < 550 Ω analog output 3 (+) active, 420 mA, load < 550 Ω output 3 (+) active, 420 mA, load < 550 Ω output 3 (+) active, 420 mA, load < 550 Ω output 3 (+) active, 420 mA, load < 550 Ω output 3 (+) active, 420 mA, load < 550 Ω output 3 (+) active, 420 mA, load < 550 Ω output 3 (+) active, 420 mA, load < 55				
(III) (6) NC4 max. 40V / 1A AC, max. 60V / 1A DC				·
(1) (7) +DO1 pulse output 1 (+) pulse width / frequency adjustable pulse output 1 (-) pulse output 1 (-) pulse width / frequency adjustable pulse output 2 (-) pul				
Inputs / Outputs	(2) AC/DC Digital			
(III) (7) +24V DC*	_			
(i) (8)	inputs / Outputs	i .		puise output 1 (-)
(ii) (8)				pulse output 2 (+) pulse width / frequency adjustable
(iii) (8) GND Holt digital input 1 (+) max. 30V digital input 1 (+) max. 30V (iii) (9) +24V DC* Holt H		i .		
(i) (9) +DI1 digital input 1 (+) max. 30V digital input 1 (-) (iii) (9) +24V DC* (ii) (10) (10) +DI2 digital input 2 (+) max. 30V digital input 2 (-) max. 30V				——————————————————————————————————————
(ii) (9)				digital input 1 (+) max. 30V
(III) (9)				
(II) (10)				_
(III) (10) GND — (III) (11) A not connected (III) (11) Y not connected (III) (11) Y not connected (III) (12) Z not connected (III) (12) not connected (III) (12) not connected (III) (13) +AO1 analog output 1 (+) active, 420 mA, load < 550 Ω (III) (13) +AO2 analog output 1 (-) (III) (13) +AO2 analog output 2 (-) 0/420 mA, load < 550 Ω (III) (14) GND — (III) (15) +AO3 analog output 3 (+) active, 420 mA, load < 550 Ω (III) (15) +AO3 analog output 3 (+) active, 420 mA, load < 550 Ω (III) (15) +AO3 analog output 3 (+) active, 420 mA, load < 550 Ω (III) (15) +AO4 analog output 3 (-) 0/420 mA (III) (16) GND — (III) (17) +AI1 analog input 4 (-) active, 420 mA, load < 550 Ω (III) (17) +AI1 analog input 1 (-) (III) (18) -AI2 analog input 2 (-) 420 mA (III) (18) -AI2 analog input 2 (-) (-) (-) (-) (-) (-) (-) (-) (-) (-)		(I) (10)	+DI2	digital input 2 (+) max. 30V
(4) AC/DC Service Interface RS-485 (II) (11)		(II) (10)	- DI2	digital input 2 (-)
(III) (11)	_ ,			
(III) (11)	1	l .		not connected
(I) (12) Z not connected (III) (12) not connected (III) (12) not connected (III) (12) not connected (III) (12) not connected (III) (13) +AO1 analog output 1 (+) active, 420 mA, load < 550 Ω (III) (13) +24V DC* — (I) (14) +AO2 analog output 2 (+) active, 420 mA, load < 550 Ω (III) (14) +AO2 analog output 2 (-) 0/420 mA (III) (15) +AO3 analog output 3 (+) active, 420 mA, load < 550 Ω (III) (15) +AO3 analog output 3 (-) 0/420 mA (III) (15) +24V DC* — (I) (16) +AO4 analog output 4 (+) active, 420 mA, load < 550 Ω (III) (16) -AO4 analog output 4 (-) active, 420 mA, load < 550 Ω (III) (16) GND — (III) (16) GND — (III) (17) +A11 analog input 1 (+) 420 mA (III) (17) +24V DC* — (I) (18) +AI2 analog input 2 (+) 420 mA (III) (18) -AI2 analog input 2 (-) (III) (19) +AI3 analog input 3 (+) 420 mA (III) (19) +AI3 analog input 3 (+) 420 mA (III) (19) +AI3 analog input 3 (-) (III) (19) +AI4 analog input 3 (-) (III) (19) +AI4 analog input 4 (-) analog input 4 (-) active, 420 mA (III) (19) +AI3 analog input 3 (-) (III) (19) +AI3 analog input 3 (-) (III) (19) +AI4 analog input 4 (-) 420 mA (III) (19) -AI3 analog input 4 (-) 420 mA (III) (19) +AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 analog input 4 (-) 420 mA (III) (19) -AI4 an	Interface RS-485	1		not connected
(ii) (12)			Υ	
(III) (12)		l .	Z	
(5) AC/DC Analog Outputs (I) (13)				
Outputs (II) (13) -AO1 analog output 1 (-) (II) (14) +AO2 analog output 2 (+) active, 420 mA, load < 550 Ω (III) (14) -AO2 analog output 2 (-) 0/420 mA (III) (15) +AO3 analog output 3 (+) active, 420 mA, load < 550 Ω (III) (15) +24V DC* — (I) (16) +AO4 analog output 4 (+) active, 420 mA, load < 550 Ω (III) (16) -AO4 analog output 4 (-) active, 420 mA, load < 550 Ω (III) (16) GND — (6) AC/DC Analog Inputs (I) (17) +AI1 analog input 1(+) 420 mA Inputs (II) (17) +24V DC* — (I) (18) +AI2 analog input 2 (+) 420 mA (II) (18) -AI2 analog input 2 (-) (III) (19) +AI3 analog input 3 (+) 420 mA (II) (19) +AI3 analog input 3 (-) (III) (19) +24V DC* — (II) (20) +AI4 analog input 4 (-) 420 mA (II) (20) -AI4 analog input 4 (-) 420 mA	(E) A C (D C A l			
(III) (13) +24V DC* — (I) (14) +AO2 analog output 2 (+) active, 420 mA, load < 550 Ω (II) (14) -AO2 analog output 2 (-) 0/420 mA (III) (15) -AO3 analog output 3 (+) active, 420 mA, load < 550 Ω (II) (15) -AO3 analog output 3 (-) 0/420 mA (III) (15) +24V DC* — (I) (16) +AO4 analog output 4 (+) active, 420 mA, load < 550 Ω (III) (16) -AO4 analog output 4 (-) active, 420 mA, load < 550 Ω (III) (17) +AI1 analog input 1 (+) 420 mA (III) (17) +24V DC* — (II) (18) +AI2 analog input 2 (+) 420 mA (III) (18) -AI2 analog input 2 (+) 420 mA (III) (18) -AI2 analog input 2 (-) (III) (19) +AI3 analog input 3 (+) 420 mA (III) (19) -AI3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (+) 420 mA (III) (20) -AI4 analog input 4 (-)				
(I) (14) +AO2 analog output 2 (+) active, 420 mA, load < 550 Ω (II) (14) -AO2 analog output 2 (-) 0/420 mA (III) (14) GND — (I) (15) +AO3 analog output 3 (+) active, 420 mA, load < 550 Ω (II) (15) +24V DC* — (I) (16) +AO4 analog output 4 (+) active, 420 mA, load < 550 Ω (III) (16) -AO4 analog output 4 (-) active, 420 mA, load < 550 Ω (III) (16) GND — (6) AC/DC Analog Inputs (I) (17) +AI1 analog input 1(+) 420 mA (II) (17) +24V DC* — (I) (18) +AI2 analog input 2 (+) 420 mA (II) (18) -AI2 analog input 2 (-) (III) (19) +AI3 analog input 3 (+) 420 mA (III) (19) +AI3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (-) active, 420 mA (III) (19) +24V DC* — (I) (20) +AI4 analog input 3 (-) (III) (20) -AI4 analog input 4 (-)	Outputs			analog output 1 (-)
(III) (14)				analog output 2 (+) active 4 20 mA load < 550 O
				· ·
(I) (15)				—
(II) (15) -AO3 analog output 3 (-) 0/420 mA (III) (15) +24V DC* — (I) (16) +AO4 analog output 4 (+) active, 420 mA, load < 550 Ω (III) (16) GND — (6) AC/DC Analog Inputs (I) (17) +AI1 analog input 1(+) 420 mA (II) (17) +24V DC* — (I) (18) +AI2 analog input 2 (+) 420 mA (II) (18) -AI2 analog input 2 (-) (III) (18) GND — (II) (19) +AI3 analog input 3 (+) 420 mA (III) (19) +AI3 analog input 3 (-) (III) (19) +AI3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (+) 420 mA (II) (20) -AI4 analog input 4 (-)				analog output 3 (+) active, 420 mA, load $< 550 \Omega$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				· ·
(II) (16)			+24V DC*	<u>– </u>
(III) (16) GND — (6) AC/DC Analog Inputs (I) (17) +Al1 analog input 1(+) 420 mA (II) (17) +24V DC* — (I) (18) +Al2 analog input 2 (+) 420 mA (II) (18) -Al2 analog input 2 (-) (III) (18) GND — (I) (19) +Al3 analog input 3 (+) 420 mA (II) (19) -Al3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +Al4 analog input 4 (+) 420 mA (II) (20) -Al4 analog input 4 (-)				analog output 4 (+) active, 420 mA, load $<$ 550 Ω
(I) (17) +Al1 analog input 1(+) 420 mA (II) (17) -A1 analog input 1(-) (III) (17) +24V DC* — (I) (18) +Al2 analog input 2 (+) 420 mA (II) (18) -Al2 analog input 2 (-) (III) (18) GND — (I) (19) +Al3 analog input 3 (+) 420 mA (II) (19) -Al3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +Al4 analog input 4 (+) 420 mA (II) (20) -Al4 analog input 4 (-)				analog output 4 (-) active, 420 mA, load $<$ 550 Ω
(II) (17)				-
(III) (17) +24V DC* — (I) (18) +AI2 analog input 2 (+) 420 mA (II) (18) -AI2 analog input 2 (-) (III) (18) GND — (I) (19) +AI3 analog input 3 (+) 420 mA (II) (19) -AI3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (+) 420 mA (II) (20) -AI4 analog input 4 (-)	_	i .		
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(III) (18) GND — (I) (19) +AI3 analog input 3 (+) 420 mA (II) (19) -AI3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (+) 420 mA (II) (20) -AI4 analog input 4 (-)				· ·
(I) (19) +AI3 analog input 3 (+) 420 mA (II) (19) -AI3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (+) 420 mA (II) (20) -AI4 analog input 4 (-)		l .		analog iliput 2 (-)
(II) (19) -AI3 analog input 3 (-) (III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (+) 420 mA (II) (20) -AI4 analog input 4 (-)				analog input 3 (+) 4 20 mA
(III) (19) +24V DC* — (I) (20) +AI4 analog input 4 (+) 420 mA (II) (20) -AI4 analog input 4 (-)		1		· ·
(I) (20) +AI4 analog input 4 (+) 420 mA (II) (20) -AI4 analog input 4 (-)				——————————————————————————————————————
(II) (20) -Al4 analog input 4 (-)				analog input 4 (+) 420 mA
· ·		l .		· ·
\/\-\-/		(III) (20)	GND	<u> </u>

* max. 200 mA = auxiliary supply (sum) for all connected sensors

Block	No. (row) (no.)	Name	Descr	iption	Cable Color
(7) AC/DC MODBUS			RS-485		2000
			4-wire	2-wire	RS-232
	(21)		-TX	-D	TXD
	(22)		+TX	+D	NA
	(23)		-RX	NA	NA
	(24)		+RX	NA	RXD
	(25)		GND	GND	GND
	(26)		SH	SH	SH
(8) AC/DC	(36)	T-	Tempe	rature -	pink
Connection area	(37)	T+	Temper	rature +	grey
velocity sensor	(38)	h-	Water	level -	yellow
verocity sensor	(39)	h+	Water	level +	green
	(40)	V-	Velo	city -	white
	(41)	v+	Veloc	city +	brown
	(42)	shield		•	

IMPORTANT

Input/output data (I/O values) are programmed in the software in the I/O main menu.

Additional elements

SIM card slot	Slot for SIM card insertion / removal					
LAN	RJ45 socket for Ethernet connection / local LAN via RJ45 cable					
LED	LED control light flashes during GSM data transfer					
F	AC version: Fuse T2A (slow blow fuse) / 250V 5×20					
Fuse	DC version: Fuse T2A (slow blow fuse) / 250V 5 × 20					

5.2. Connecting the Sensors

Sensors are connected to the connector blocks according to the specific sensor types. The voltage supply of the sensors is provided by the transmitter.

ACAUTION

- Before connecting or disconnecting the cable, be sure the power is switched off.
- Sensor connection must be carried out in accordance to wiring diagram, for instance the cable colors must match with pin assignment.
- For connecting the cable sheath should only be removed for a maximum length of 1.6 in. (4 cm).
- The stripped length of the cable has to be shorter than 0.3 in. (7 mm).
- Stranded ends should be either provided with ferrules or tinned.
- Avoid too tight clamping when attaching the cable to the transmitter. Compression of the converter cable might lead to short-circuit between the signal and the shielding and might damage the transmitter.
- After connecting the cable, the cable bushing underneath the enclosure should be tightened.
- All cables must be installed in order to protect cables from mechanical destruction. Mount the cables firmly to the wall, without any loops and crossovers and in sufficient distance to moving parts to avoid accidents caused by stumbling.

5.2.1. Connecting Area Velocity Sensor



No.	Name Cable Color	
(71)	Not used	_
(72)	Not used	_
(73)	Sensor - h - B	Yellow
(74)	Sensor - h - A	Green
(75)	GND	_
(76)	GND	Black
(77)	Sensor – v - B	White
(78)	Sensor – v - A	Brown

v: velocity (measured by velocity sensor)

h: height (water level measured by water level sensor

Figure 9: Pin assignment (# 71-78) for the connection of area velocity sensor

5.2.1.1. Connecting Multiple Area Velocity Sensors

The IS-6000 Doppler meter allows the connection of up to 3 area velocity sensors for flow velocity measurements at up to 3 measurement spots in one cross-section. For the connection of multiple sensors, additional boards have to be installed. Depending on the transmitter enclosure type, an additional enclosure might be needed. Costumer-specific connection diagrams will be provided regarding the number of sensors and enclosure type. The connected sensors are identified by definition of specific sensor IDs and can be parameterized individually via the software.

5.2.2. RS-485 /RS-232 Modbus Configuration

NOTE: The 120-Ohm termination resistor is only needed for the last participant / device on the bus.

Upon delivery, the dip switch settings at the MODBUS module are set to RS-485 4-wire (standard setting). For other customer specific settings, please contact our service engineers.



		Name / Description		n
	No.	RS-485 4-wire	RS-485	RS-232
		(standard)	2-wire	K3-232
(7) AC/DC	(21)	-TX	-D	TXD
	(22)	+TX	+D	NA*
MODBUS	(23)	-RX	NA*	NA*
	(24)	+RX	NA*	RXD
RS-485 /	(25)	GND	GND	GND
RS-232	(26)	SH	SH	SH

^{*} NA: not assigned/used

Figure 10: Pin assignments # 21-26 for connection on RS-485 2-wire / 4-wire and RS-232 (pin assignment for aluminium enclosure – integrated 4G/3G/2G modem)

5.3. Final Check of Electrical Connections

On completion of the electrical wiring and before connecting the device to the power supply, make sure that the supply voltage matches the specification on the name plate and check the following instructions:

IMPORTANT

- Visual inspection for damages on transmitter, cables, sensors, and cables glands.
- Make sure the enclosure is properly fitted, clean and undamaged. All screws must be firmly tightened.
- All cable glands must be installed, tightened, and sealed.
- Use blind plugs for unused cable entries.
- Lay the cables in a downward hanging loop just before the cable entry so that possible moisture can collect in the loop and does not reach the cable entry.
- Adjustment of cables must be carried out by the manufacturer only.
- Mounted cables must have adequate strain relief.
- Do not bend cables to avoid cable breaks.
- Defective cables must be replaced by the manufacturer only.

NOTE: For devices with external 3G/2G router or integrated 4G/3G/2G modem, it is recommended to insert the SIM card and connect the 4G/LTE dipole antenna prior to turning on the power supply.

ACAUTION

AFTER ELECTRICAL CONNECTION CHECK AGAIN:

- VISUAL INSPECTION FOR DAMAGES ON TRANSMITTER, CABLES, SENSORS AND CABLES GLANDS.
- ENSURE THAT THE ENCLOSURE IS PROPERLY FITTED, CLEAN AND UNDAMAGED.
- ALL CABLE GLANDS ARE INSTALLED, TIGHTENED AND SEALED.
- USE BLIND PLUGS FOR UNUSED CABLE ENTRIES.

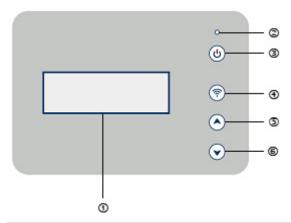
ACAUTION

- ADJUSTMENT OF CABLES MUST BE CARRIED OUT BY THE MANUFACTURER ONLY.
- MOUNTED CABLES MUST BE STRAIN RELIEVED.
- DO NOT BEND CABLES TO AVOID CABLE BREAKS.
- DEFECT CABLES MUST BE REPLACED BY THE MANUFACTURER ONLY.

6. **COMMUNICATION WITH TRANSMITTER**

6.1. Control Panel and LC-Display

The transmitter does not have an extra power switch. On connecting the transmitter to a power supply the LC-Display shows the programmed parameters and the control panel can be operated (see Figure 11).



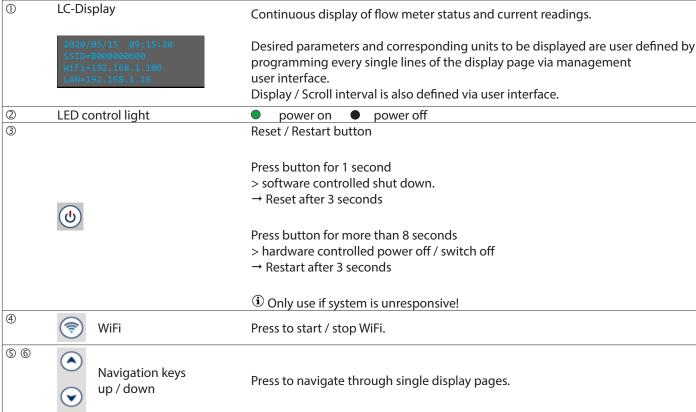


Figure 11: Control panel and display functions

For programming and operation simply connect your PC, notebook, tablet, or smart phone to the flow computer of the transmitter via WiFi or LAN by calling up the graphic user interface (GUI) using a standard web browser.

6.2. Wireless Communication WiFi

(1) Switch on power supply for transmitter.

The display will show the predefined specific SSID (access point name) of the device: for example B000000600 (corresponding to serial number of device).

2020/05/15 09:15:20 LAN=192.168.1.16 WiFi=192.168.1.100 SSID=B000000600

(2) Start WiFi by pressing WiFi button of transmitter.



Wait for status message "WIFI on!".



If WiFi IP address does not display, reboot the meter.

- (3) Switch on your PC, notebook, tablet or smartphone and establish WiFi connection according to your operating system.
- (4) Select predefined SSID to connect transmitter with your device.

Enter the **WiFi password** according to the network number printed below the manufactured date on the nameplate (see 9 on nameplate). Enter only numbers without characters or space! Example:

number: B131104/1208 > password: 1311041208

Then open your web browser and type the following IP address in the address bar: 192.168.1.100

The IP address is also displayed on the transmitter display under WiFi.

(5) If your device is connected to the transmitter, the login page of the GUI (graphical user interface) opens.



(6) Log in by entering user name and password to start working with the user interface.

Username: service Password: badger6000

NOTE: Cookies and JavaScript must be enabled in your browser settings to login.

If settings are not activated, the following error messages appear:



6.3. Communication to the Transmitter via Ethernet LAN

Use RJ45 cable to connect transmitter with your PC.

Then establish connection corresponding to individual network settings or ask your network administrator for assistance.

Default setting: Automatic assignment of the IP address via DHCP.

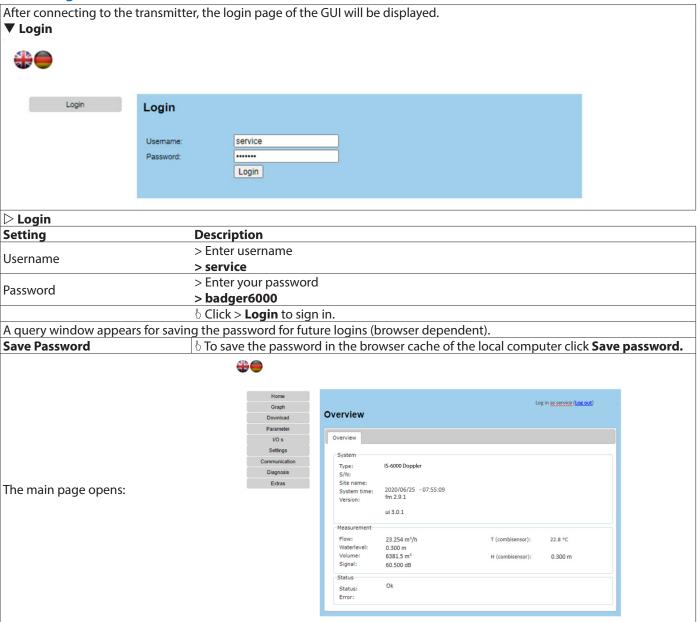
The corresponding IP address is displayed on the transmitter display under LAN.

Manual IP address assignment (without DHCP): If a static IP address, subnet mask and default gateway are required, the parameters can be assigned manually by deactivating DHCP and enter new IP address and network parameters.

The settings are changed in GUI in the main menu ▶ **Communication** under ▷ Network LAN.

7. PROGRAMMING

7.1. Login



7.1.1. User Groups and Access Rights

The following user groups with different individual user rights are preset by the manufacturer.

Username (name of user group)	Rights	Password
User	Read data	1234
	 Read parameters and settings 	
	 Download data files 	
Service	In addition to the rights under the login <i>User</i> : • Set, change and save transmitter settings	badger6000
	 Definition of units and user defined measurement parameters 	
	Restart of volume calculation	
	Software update	
	Backup and restore settings	

IMPORTANT

Passwords are predefined and can only be changed by the manufacturer. The manufacturer has full access to the unit and data for online analysis, troubleshooting and debugging.

7.2. Menu Structure

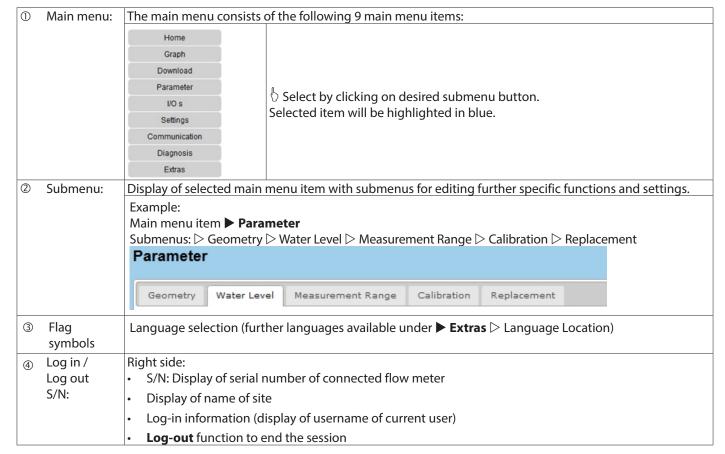
The user interface is clearly structured and shows four function areas:

① Main menu, ② Submenu, ③ Language selection, ④ Log in / Log out









7.2.1. Overview of Main Menu Items and Function of Corresponding Submenus

7.2.1. Overview of Main P	Menta items and Function of Corresponding Submenus
Home	Overview Overview status of measuring system. (system specification, name measuring site, display current readings, status information, error messages, version no.)
Graph	\triangleright 3 Days \triangleright Current \triangleright History \triangleright v-Profile \triangleright Settings Data visualization (real time data, customized time series, velocity profile)
Download	 Download Setting Data retrieval and customizing settings for data transfer
Parameter	□ Geometry □ Water level □ Measurement Range □ Calibration □ Replacement □ Replacement Parameterization of measuring profile, settings for water level measurement, measurement range, calibration, discharge calculation replacement function
I/Os	 ➢ Analog In ➢ Analog Out ➢ Digital In ➢ Digital Out ➢ User values I/Os settings for digital, analog in- and outputs, pulse outputs, user defined outputs
Settings	\triangleright Logging \triangleright Units \triangleright Displayed Units \triangleright Totalizer Customized settings for data logging, units, volume totalizer.
Communication	Network > SMS > FTP > Modbus > Serial Selection of communication type (LAN, FTP, Modbus, Serial) / communication interface to sensor, settings for SMS alarm
Diagnosis	 ▶ Log Files ▷ Data Display of log file content for analysis, data summary sheet.
Extras	► Language Date Time LC-Display Power Management Backup & Update Settings for language, data transfer, date and time, time synchronization, settings for power management (during battery operation) and options for backup and software update.
HW Configuration	 DSP Configuration Settings for DSP (Digital Signal Processing) configuration. This menu is only visible and editable by the manufacturer or authorized users.

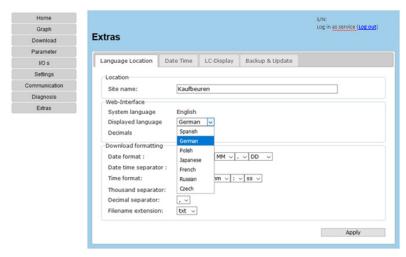
For the desc	For the description of the user interface (GUI), the following symbols are used:	
>	Main menu item	
\triangleright	Submenu	
8	Mouse click, left mouse button	
>	Type, enter, etc.	
▼	Select from drop-down list	
	Checkbox, disabled > function not active	
$\overline{\checkmark}$	Checkbox, enabled > function active	
Update	Commands are written in bold	
Link	Link; click on link to activate function	
(i)	Notice, information	
[1]	Literature reference	

7.3. Settings for Language and Location

Default language at first start is English. To change the displayed language, click main menu item > **Extras.** The corresponding flag symbol of the selected language will be displayed. To change between languages, click the flag symbol.

▼ Extras





> Language Location		
Setting	Description	
Location		
Site name	> Enter name of measuring site.	
	Site name is displayed on start page ▼ Home – Overview.	
Web-Interface		
System language	English	
Displayed language		
▼Spanish	> Select language from drop-down list.	
Czech		
	♦ Click Apply to save settings.	
	The corresponding flag symbol of the selected language will be displayed.	
	b Click the flag symbol to change between languages.	
	For more settings, see "7.2.1. Overview of Main Menu Items and Function of Corresponding	
	Submenus" on page 31.	

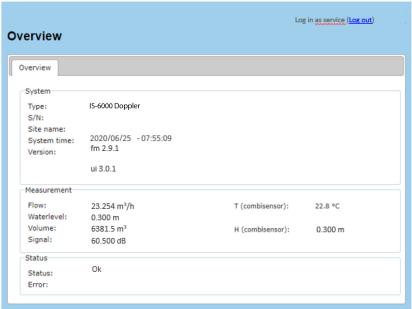
7.4. Home - Overview



► Home - Overview

○ Overview

General information on measuring system and status.



▷ Overview	> Overview			
Parameter	Setting	Description		
System	Туре	Display name of connected measuring system.		
	S/N	Display of serial number of measuring system; automatically assigned.		
	Site name	Display name measuring site. Name entry field under ▼ Extras ▷ Language Location.		
	System time	Display system time		
	Version	Current version numbers of hard- and software fm: version flow meter ui: version GUI (user interface).		
	Flow	Display of current value discharge.		
	Water level	Display of current water level.		
	Volume	Display of current value total volume.		
Measurement	Signal	Display of current signal value.		
	T (combisensor)	Display of current water temperature		
	H (combisensor)	Display of current water level value		
Status	Status	Display device status.		
	Error	Display of date, time, error codes (binary code) and error description. ① Note that on the transmitter LCD the specific error code will not be displayed. Error message displayed on transmitter: ERROR. Refer to user interface for error code.		

7.5. Graph - Data Visualization



▶ Graph

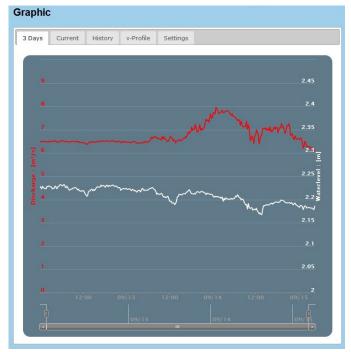
 \triangleright 3 Days \triangleright Current \triangleright History \triangleright v-Profile \triangleright Settings

This menu consists of 5 functions and provides flexible options for graphical display of data, for example

- online data presentation (Current)
- · data point information by clicking directly on data curve
- data display over a user defined time period, data history (3 Days, History)
- velocity profile (v-Profile)
- customized parameters, color selection and scaling (Settings)

7.5.1. Three-Day Display

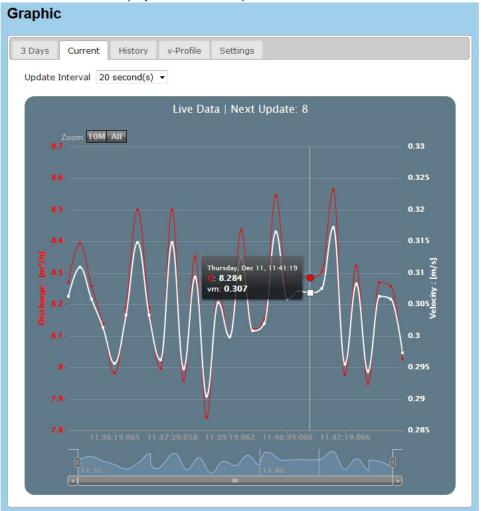
Display time series over max. 3 days.



▷ 3 Days			
Setting	Description		
3 Days	Data display of last 3 days.		
	b Click on single data point for display of measurement value.		
Adjustable time bar	Select time span by adjusting the time bar; click with left mouse button on the end of the bar, hold down the left mouse button and drag bar in position for desired date		
	0 16:00 03/17 08:00		

7.5.2. Current

Live / real time data display in customized update interval.

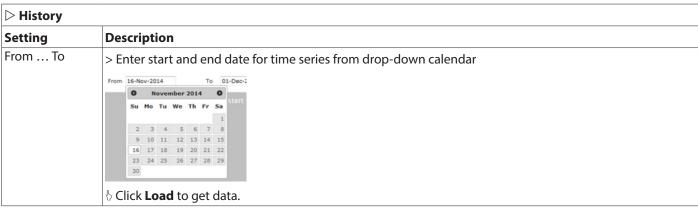


▷ Current		
Setting	Description	
Update Interval ▼ 530 seconds	> Select time for data update interval from drop-down list.	
Zoom	Zoom options data display.	
10M - All	 Click 10M to display data of last 10 minutes since opening page in selected update interval. Click All to display all data since opening page in selected update interval. 	
	Adjustable time bar: Zoom function for data display in user defined time span by adjusting the time bar. Click with left mouse button on the end of the bar, hold down the left mouse button and drag bar in position for desired time interval for data display.	
	b Click on single data point for display of measurement values.	

7.5.3. History

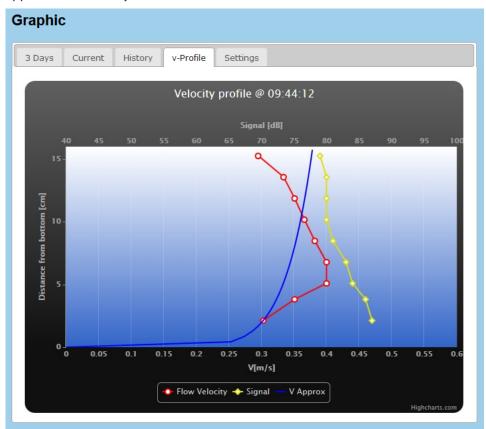
Data display over user-defined time span.

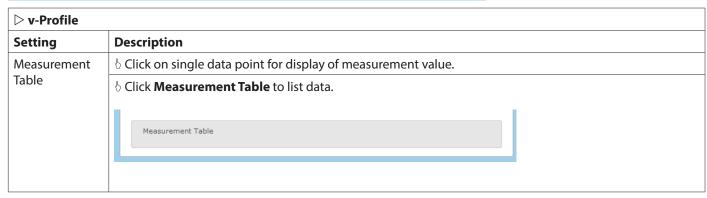




7.5.4. Velocity Profile

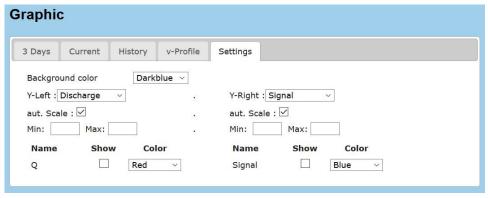
Display of velocity profile velocity (velocity lower X-axis) / distance from bottom (Y-axis), Signal (upper X-axis) and approximated velocity curve.





7.5.5. Settings

Parameter selection of the two Y-axes and display options.



Settings	
Setting	Description
Background Color ▼ Dark blue HV Blue ()	> Select color for background of graphic.
Y-Left ▼ Discharge Velocity Volume ()	> Select parameter to be displayed on left Y-axis from drop-down list: Discharge Velocity Volume Waterlevel Area Temperature Signal Voltage Unitless
Y-Right ▼ Discharge Velocity Volume ()	> Select parameter to be displayed on right Y-axis from drop-down list: Discharge Velocity Volume Waterlevel Area Temperature Signal Voltage Unitless
aut. Scale: □	> ☑ Tick checkbox to activate automatic scaling.
Min:	> Enter minimum value to be displayed. (entry only possible if automatic scaling is disabled)
Max:	> Enter maximum value to be displayed. (entry only possible if automatic scaling is disabled)
List Name	Display of selected parameter.
Show □	> ☑ Tick checkbox to show listed parameter.
Color ▼ Red Yellow ()	> Select display color.

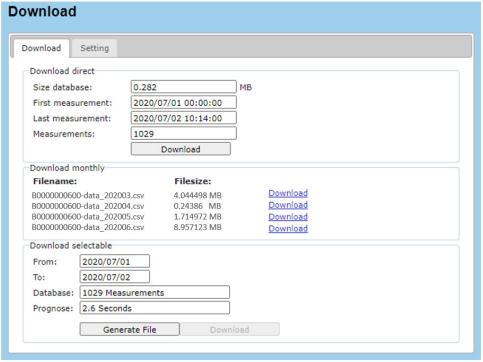
7.6. Download, Data Transfer



7.6.1. Download

Settings for data download options.

- · Download of entire raw data.
- · Download of monthly recorded data.
- Download of data over a user defined period.



Download					
Download direct					
	in SI units to a CSV-file. Units are not displayed in raw data file.				
Setting	Description				
Size database	Display data base size.				
First measurement	Display of date and time of first measurement.				
First measurement	Display of date and time of last recorded measurement.				
Measurements	Display of total numbers of measurements.				
Daniel and magnetic trans	Click Download to save data file (data.csv). Depending on your browser settings a dialog box opens to open or save the data file. Confirm with > OK in the dialog box to start data download or press > cancel to abort data transfer.				
Download monthly	Download of monthly recorded data. File name serial no-data_yyyymm.csv will be displayed and can be downloaded directly by clicking by Download.				
Download selectable					
 For selection of data 	ned data sets and units for user defined period. a sets and units go to ▶ Download ▷ Setting. ng see under ▶ Extras ▷ Language Location.				
From	> Enter measurement start date from drop-down calendar.				
То	> Enter measurement end date from drop-down calendar.				
Database	Display of total numbers of measurements.				
Prognosis	Display of estimated download time.				
	A dialog box opens to display download progress. download preparation The download file will be created This process will take some time Start Cancel Close				
	 Click Start for download. While downloading data the remaining time is indicated. Or click Cancel to abort. 				
	The download file will be created This process will take some time Complete				
	Start Cancel Close				
	If download is complete & click Close to return to main window. Then & click highlighted button Download . Depending on your browser settings a dialog box opens to save or open the data file. Select the desired option in the dialog box (for example confirm with > OK or > cancel to abort data transfer) to complete data download. Default file name: System name_device serial number_start date yyyymmdd – last date yyyymmdd.csv				

7.6.2. Setting

Settings for selection of parameters and corresponding units (SI units or displayed units) for download-file under Download selectable.



Setting	Description				
Use SI units	☑ Tick checkbox to download data in SI units.				
Use Display units	☑ Tick checkbox to download data in displayed units.				
	3 Before you start to choose the data, please check and define the displayed units in the main				
	menu ▶ Settings under ▷ Displayed Units.				
All Data	☑ Tick checkbox to select all data shown below.				
	Do not tick if you want to select single parameters.				
Insert Unit in CSV Header	☑ Tick checkbox to display unit in csv-file.				
	In the following list you can also specify single parameters (Length, Time, Time, Q, Velocity,				
	Volume, Temperature, Unitless, Concentration, Signal, Voltage) for download by ticking				
	the corresponding checkboxes.				
	NOTE: The list comprises and shows all possible parameters that can be set for all measuring systems using the specified transmitter type and not only for the connected system.				

7.7. Parameter - Parameterization



▶ Parameter

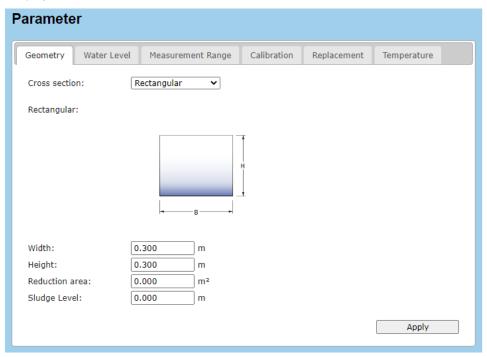
The menu provides further options for

- Definition of cross-section parameters
- Settings for level measurement
- Parameter setting for discharge calculation
- Calibration
- Replacement function for discharge calculation
- Setting a temperature offset to a reference measurement

7.7.1. Geometry

Definition of cross-section shapes and dimensions, geometrical values of sewers, drains and pipelines (according to DIN 4263 [1]).

③ Before you start the parameter input, please check and define the displayed units in the main menu ▶ **Settings** under ▷ Displayed Units.



▷ Geometry				
Setting	Description			
CrossSection ▼ Circular	CrossSection: Circular Circular:			
	Diameter: 0.210 m Sludge Level: 0.000 m Reduction area: 0 m²			
Diameter	> Enter pipe diameter (D)			
Sludge Level	> Enter thickness of sludge / sediment layer (see Figure 12 on page 47).			
Reduction area	> Enter 0 (recommended) or value for cross section area reduction (for example due to installations in the pipe or channel). b Click Apply to save settings for circular cross-section.			
CrossSection ▼ Rectangular	CrossSection: Rectangular ▼ Rectangular:			
	Width: 1.000 m Height: 1.000 m Reduction area: 0 m² Sludge Level: 0.000 m			
Width	> Enter width (B)			
Height	> Enter height (H)			
Reduction area	> Enter 0 (recommended) or value for cross section area reduction (for example due to installations in the pipe or channel).			
Sludge Level	> Enter thickness of sludge / sediment layer (see Figure 12 on page 47). b Click Apply to save settings for rectangular cross-section.			

 ○ Geometry	
CrossSection ▼ U-Profile	CrossSection: U Profile:
	Height: 0.190 m Radius: 0.120 m Reduction area: m² Sludge Level: 0.000 m
Height	> Enter height (H) of cross-section as shown in drawing above.
Radius	> Enter radius of semi circle.
Reduction area	> Enter 0 (recommended) or value for cross section area reduction (for example due to installations in the pipe or channel).
Sludge Level	> Enter thickness of sludge / sediment layer (see Figure 12 on page 47).
	b Click Apply to save settings for trapezoid cross-section.
▼ Trapezoid	CrossSection: Trapezoid ▼ Trapezoid:
	Width: 0.200 m Height: 0.050 m Angle left: 44 ° Angle right: 55 ° Reduction area: 0 m² Sludge Level: 0.000 m
Width	> Enter width (B).
Height	> Enter height (H).
Angle_left	> Enter left angle (α).
Angle_right	> Enter right angle (β).
Reduction area	> Enter 0 (recommended) or value for cross section area reduction (for example due to installations in the pipe or channel).
Sludge Level	> Enter thickness of sludge / sediment layer (see Figure 12 on page 47). b Click Apply to save settings for trapezoid cross-section.
	V Click Apply to save settings for trapezola cross-section.

▷ Geometry			
CrossSection ▼ J Trapezoid	CrossSection: J Trapezoid: B H H L D H H D D H H D D D D D D		
	Width B: 0.000 m		
	Width b: 0.000 m		
	Height H: 0.000 m		
	Height h: 0.000 m		
	Reduction area: m²		
	Sludge Level: 0.000 m		
Width B	> Enter upper width (B).		
Width b	> Enter lower width (b).		
Height H	> Enter upper height H.		
Height h	> Enter lower height h.		
Reduction area	> Enter 0 (recommended) or value for cross section area reduction (for example due to installations in the pipe or channel).		
Sludge Level	> Enter thickness of sludge / sediment layer (see Fi. 22).		
	b Click Apply to save settings for J trapezoid cross-section.		
▼ Egg	Egg (DIN 4263): H=3r H=3r Radius: Reduction area: Sludge Level: 0.010 m		
Radius	> Enter radius.		
Reduction area	> Enter 0 (recommended) or value for cross section area reduction (for example due to installations in the pipe or channel).		
Sludge Level	> Enter thickness of sludge / sediment layer (see Figure 12 on page 47).		
	b Click Apply to save settings for egg cross-section.		

▷ Geometry	
CrossSection ▼ Mouth	CrossSection: Mouth Mouth (DIN 4263): H=1.5r B=2r
	Radius: 0.220 m Reduction area: 0 m² Sludge Level: 0.010 m
Radius	> Enter radius (r).
Reduction area	> Enter 0 (recommended) or value for cross section area reduction (for example due to installations in the pipe or channel).
Sludge Level	> Enter thickness of sludge / sediment layer (see Figure 12 on page 47). b Click Apply to save settings for mouth cross-section.
▼ Irregular Polynom	Tregular Enable: # x-Axis: y-Axis: [m] 1 1.500 1.950 + 2 1.500 1.550 + 3 2.000 0.750 + 4 3.000 0.350 + 5 4.000 0.250 + 6 5.000 0.210 + 7 6.000 0.000 + 8 7.000 0.500 + 9 7.800 0.280 + 10 8.700 0.600 + 11 9.200 0.900 + 12 10.100 1.150 + 13 10.100 1.950 +
x-Axis	> Enter values for width (x)
y-Axis	> Enter values for cross section height (y)
+ -	> Click + to add row for additional values or – to delete values. b Click Apply to save settings for irregular cross-section.

7.7.1.1. Sludge Level

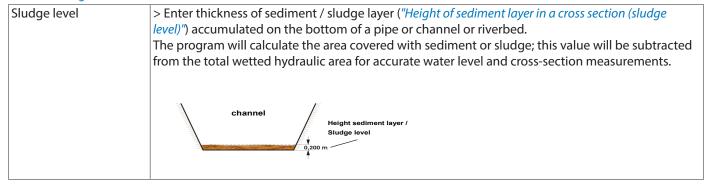
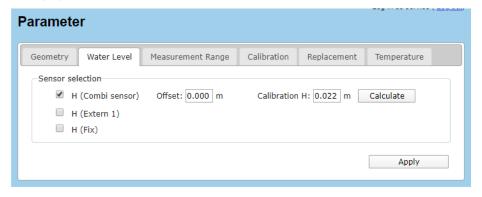


Figure 12: Height of sediment layer in a cross section (sludge level)

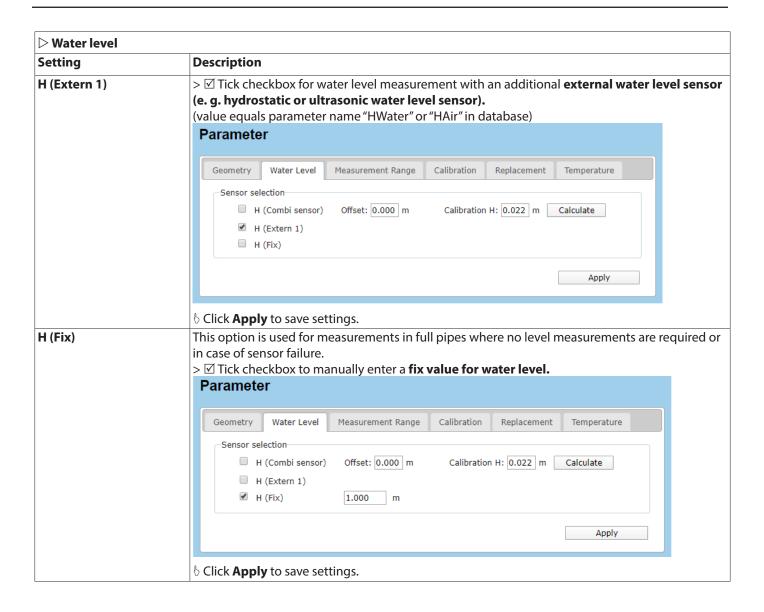
7.7.2. Water Level

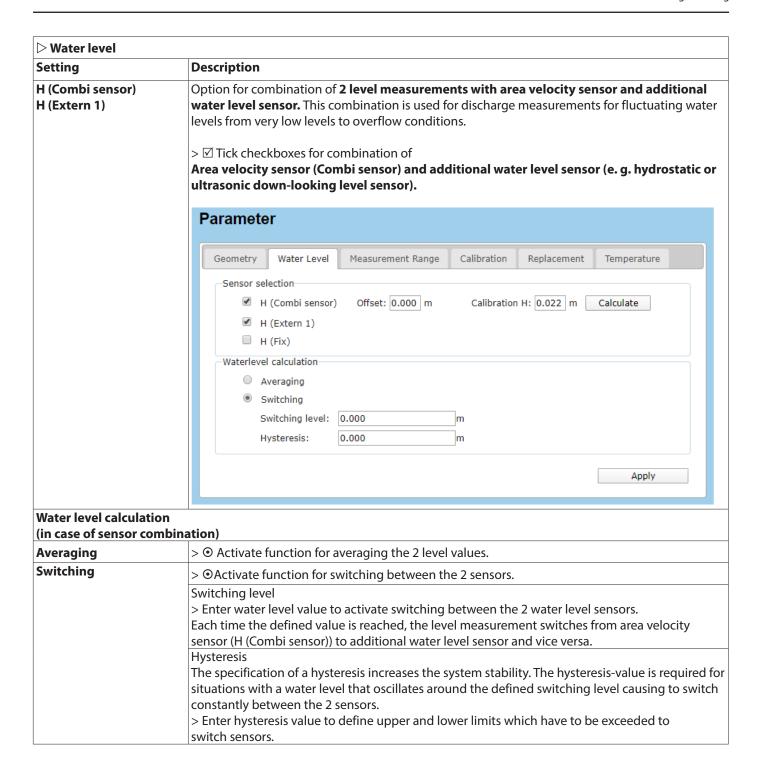
Select method for water level measurement depending on sensor type and sensor position in cross-section.

- H (Combi sensor): water level measurement with area velocity sensor.
- H (Extern 1): water level measurement with additional water level sensor (for example, hydrostatic pressure sensor or non-contact ultrasonic sensor).
- H (Fix): fix value for water level.



	> Water level				
Setting	Description				
Sensor selection					
 H (Combi sensor) Option for standard use. Measurement of water level from bottom to top of water surface. > ☑ Tick checkbox for integrated ultrasonic water level measurement with area velocity s installed on the bottom of cross-section. (value equals parameter name "HUS" in database) NOTE: Min. water level > 1.6 in. (4 cm).					
	b Click Apply to save settings.				
Offset	> Enter offset value for area velocity sensor (sensor specific) (sensor offset = height mounting plate + height sensor housing) = 0.9 in. (22 mm)				
Calibration H	> Enter water level value from an external water level measurement (e.g. from water level gauge) if a deviation with the measured water level value from area velocity sensor occurs. \$\(\text{Click Calculate for correction/adoption of measured value.} \) \$\(\text{Click Apply to save settings.} \)				

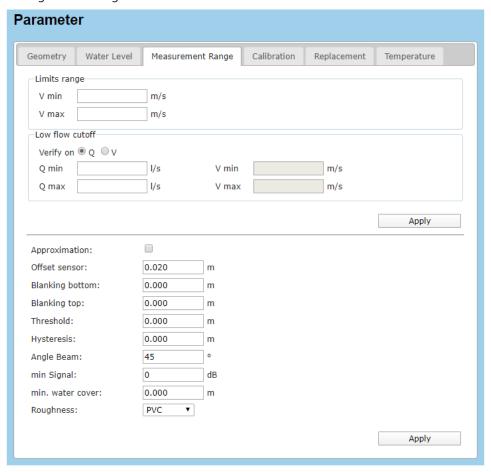




▷ Water level	
Setting	Description
Switching (continued)	There are two possible situations depending of the direction to which the water level changes.
	Situation A
	The water level is higher than value of Switching level $+$ (0.5 \times Hysteresis). Water level of additional water level sensor will be used.
	Not before the water level falls below the value Switching level – $(0.5 \times \text{Hysteresis})$ software is switching automatically, and water level of area velocity sensor will be used.
	Situation B The water level is lower than value Switching level – $(0.5 \times \text{Hysteresis})$). Water level of area velocity sensor will be used.
	Not before the water level rises above the value of Switching value $+$ (0.5 \times Hysteresis) software is switching automatically, and water level of additional water level sensor will be used.

7.7.3. Measurement Range

Settings for discharge calculation.



Setting	Description	Description				
Limits Range	> Enter minimum and / or maximum for velocity value V for plausibility check.					
V min V max	-Limits range-					
VIIIAX	V min	cm/s	If no range is set, all V-values of the measurement are used for Q calculation.			
	V max	cm/s	used for Q calculation.			
	-Limits range					
	V min 30	cm/s	V- values from 30 cm/s are used for Q calculation. (V > 30 cm/s)			
	V max	cm/s	(V > 30 CHI) 3)			
	-Limits range					
	V min	cm/s	V-values lower than 1000 cm/s are used for Q calculation. $(V < 1000 \text{ cm/s})$			
	V max 1000	cm/s	(1000 (11//3)			
	-Limits range					
	V min 30	cm/s	V-values > 30 cm/s and < 1200 cm/ are used for Q calculation. (30 cm/s < V < 1200 cm/s)			
	V max 1200	cm/s	Calculation. (50 cm/s < V < 1200 cm/s)			

	ischarge calculatio	on				
Setting	Description					
Low flow cut off	i Values defined i	n the range of t	the low flow c	ut off a	are set to 0.	
	> Enter range of very low and therefore often unsteady discharge (Q) or velocity (v) values.					
	Measurement valu displayed as zero o			table ra	ange will be set to zero a	and will also be
Verify on						
Q/V	> ☑ Tick checkbox	to choose option	on for Q- or V-	- values	S	
Q min / Q max	> Enter minimum a	and / or maximu	um for discha	rge valı	ue.	
V min / V max	> Enter minimum a					
	Low flow cutoff			•		
	Verify on ☑ Q □ V					
	Q min	l/s \	/ min		cm/s	
			/ max		cm/s	
	Q max	1/5	/ IIIdx		CITI/S	
Sensor parametrization						
(option for connection of up	to 3 area velocity s	ensors)				
(option of comments of cap		,				
(i) Note that sensor names (acturer.			
Alignment horizontal		ot activated.				
		n if measureme	ent direction	of area	a velocity sensor is vert i	ical
	(default setting).					
	Sensor:	#1 ID: 1088	#2 ID; 102		#3 ID: 103	
	Allignment horizontal:					
	Approximation:			1		
	Offset sensor:	0.02 m	0.02	m	0.02 m	
	Blanking bottom: Blanking top:	0.00 m	0	m m	0 m	
	Threshold:	0.00 m	0	m	0 m	
	Hysteresis:	0.00 m	0	m	0 m	
	Angle Beam:	45 °	45		45 °	
	min Signal:	40 dB	40	dB	40 dB	
	Roughness:	Rock ~	Rock ~		Rock ~	
					Apply	
Alignment beginned	> □ Tigle about the o	. :6		of 0400		routically
Alignment horizontal	I I				a velocity sensor is not v iter level sensor is requi	•
	Sensor:	#1 ID: 1088	#2 ID: 102		#3 ID: 103	
	Allignment horizontal:	☑	✓		✓	
	Offset sensor:	0.02 m	0.02	m	0.02 m	
	Threshold:	0.00 m	0	m	0 m	
	Hysteresis:	0.00 m	0	m	0 m	
	Angle Beam:	45 °	45	0	45 °	
	min Signal:	40 dB	40	dB	40 dB	
					Apply	
Approximation	> ☑ Tick checkbox	k for approxima	tion of veloci	ty curv	e.	
Offset Sensor					the pipe or channel wa	ll due to sediment
	· ·				oe adjusted (see Figure k	
	> Enter difference	of water lovels	value moacura	ad by a	rea velocity sensor and	reference water
	lovel This value w					icicience water

Measurement Range / [
Setting	Description					
Offset Sensor (continued)	h ₁ water level area velocity sensor h ₂ reference level sensor offset = h ₂ - h ₁					
Blanking bottom	> Enter value for adjustable distance above channel- or riverbed that will be excluded in measurement of velocity profile to eliminate measuring inaccuracies due to interference of irregular currents or turbulences around sensor housing.					
Blanking top	> Enter distance value for adjustable zone below water surface that will not be considered for measuring depending on water level.					
Threshold	Only applicable for horizontal orientation. Flow velocity measurement only starts if minimum water level $+$ 0.5 \times hysteresis value is exceeded.					
Hysteresis	 > Enter value for minimum water level value. The specification of a hysteresis increases the system stability. The hysteresis-value is required for situations with a water level that oscillates around the defined threshold causing the velocity measurement constantly being switched off and on. > Enter hysteresis value to define upper and lower limits which have to be exceeded to start/stop velocity measurement. Threshold and hysteresis are values used by the software to determine if velocity measurement depending on the current water level is active or not. There are two possible situations depending of the direction to which the water level changes. 					
	Situation A The water level is higher than value of Threshold + (0.5 × Hysteresis). The velocity measurement will be activated. If the water level falls below the value Threshold – (0.5 × Hysteresis). The velocity measurement will be stopped.					
	Situation B The water level is lower than value Threshold – (0.5 × Hysteresis). The velocity measurement will be stopped. If the water level is rising, the measurement will only start if the value of the water level is greater than Threshold + (0.5 × Hysteresis).					
	If the water level rises above the value of Threshold + (0.5 \times Hysteresis) the velocity measurement will be activated.					
Angle Beam	Default setting: 45° (angle beam for vertical measurement direction of area velocity sensor) If angle beam deviates from 45° due to installation condition (measurement direction is not					
Min Signal	vertically), the deviation has to be measured manually and recalculated. > Enter value for minimal signal strength from which measurement is activated. Example: 50 dB => measurement values with signal strengths > 50 dB are considered for discharge calculation. If no value is entered, signal strengths lower than 35 dB are considered to be no signal at all.					

Setting	Description			
Min. water cover-	Enter height above the channel/pipe floor, above which flow measurement is activated. No			
	measurement values will be recorded if the water level falls below this threshold.			
	Default value: 0.000 m.			
Roughness	> Select the material of channel surface to define specific roughness values of channel-,			
▼ Rock,	riverbed or pipe:			
Stone,	Rock			
Sand, ()	Stone			
PE	Sand			
	Earth			
	Concrete			
	Cement			
	PVC			
	PE			
	The empirical values for different materials are included in approximation formula for the			
	velocity curve.			
	Smoother surfaces have generally lower roughness coefficient values and rougher surfaces have higher values.			
	b Click Apply to save settings.			

7.7.4. Calibration

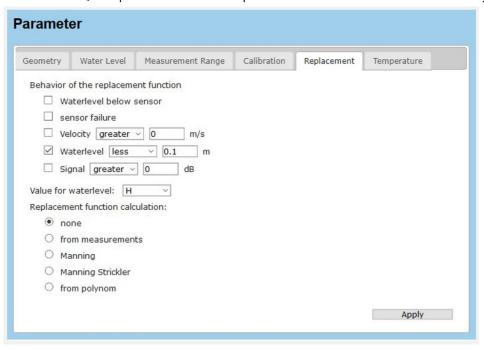
Settings for calibration through comparative measurement with reference device. Example for 5 measurements:



▷ Calibration ③ Before you start to enter values, please check and define the displayed units in the main menu ▶ Settings under Displayed Units. Enter values for Q meas (IS-6000 Doppler) and Q ref (reference device) in table of values: Description Setting Date > Enter date. > Enter water level. Q meas > Enter measured Q value. Q ref > Enter reference Q value (from reference device). □ active / > Tick checkbox to activate or delete value pair for calibration curve. □ delete b Click **Apply** to save settings. Values are displayed in the list above. b Click **Add new measurement** to enter additional values. Definition and graph of regression for calibration curve within discharge range (Q min / Q max): Active □ / ☑ > ☑ Tick checkbox to enable curve fitting. Fit > Select curve fitting options from drop-down menu. **▼** linear polynomial 2nd polynomial 3rd polynomial 4th Q max > Enter maximum for discharge value. Q min > Enter minimum for discharge value. R-Coefficient > Shows calculated regression coefficient.

7.7.5. Replacement

The replacement function provides different methods to calculate flow (Q). This option is applied in case of sensor failure or if calculation of Q is required below or above preset min. and max. limit values for velocity, water level or signal strength.



Behavior of replacement function			
Setting	Description		
☐ Waterlevel below sensor	> ☑ Tick checkbox if no measurement is possible due to too low water level for proper measurement.		
☐ Sensor failure	> ☑ Tick checkbox in case of sensor failure.		
□ Velocity	> 🗹 Tick checkbox to activate replacement function, if current measurement value exceeds or falls below the defined limit for flow velocity.		
	> Enter velocity limit value.		
	less = replacement function is activated if current measurement value falls below the defined limit value.		
	greater = replacement function is activated if current measurement value exceeds the defined limit value.		
□ Waterlevel	> 🗹 Tick checkbox to activate replacement function if current measurement value exceeds or falls below the defined limit for water level.		
	> Enter water level limit value.		
	less = replacement function is activated if current measurement value falls below the defined limit value.		
	greater = replacement function is activated if current measurement value exceeds the defined limit value.		

Behavior of replacement	nt function					
Setting	Description					
□ Signal	> \(\text{Tick checkbox to activate replacement function if current measurement value exfalls below the defined limit for signal strength.}					
	> Enter signal lim	it in dB				
	limit value.			current measurement value falls below the defined ed if current measurement value exceeds the defined		
Value for waterlevel ▼ H HWater Hair	> Select which water level parameter will be used for checking if replacement function will be applied.					
Replacement function	calculation					
O none	> ⊙ Tick checkbo	x if no repla	acement functi	ion shall be used for discharge calculation.		
○ from	> O Tick checkbo	x to calcula	ite Q from W/Q	(water level / discharge) relation.		
measurements	Replacement function calculation:					
	none none					
	from measurements					
	© Manning					
	Manning Strickler					
	from polynom					
	W-Q measurements:					
	Date	W [m]	Q [m³/h]	active delete		
	2014-07-01	0.05	5.00			
	2014-07-02	0.08	7.00			
	2014-07-03	0.09	7.50			
	2014-07-02	0.12	15.00			
	2014-07-01	0.16	22.00			
	2014-07-01	0.20	36.00			
	Add Measurement	Redraw				
	Fit:	W mir		Q min: 0.00 m³/h		
	polynomial 2nd ▼		x: 0.21 m	Q max: 50 m³/h		
	F-1,11-11-11-11-11-11-11-11-11-11-11-11-1			Z		

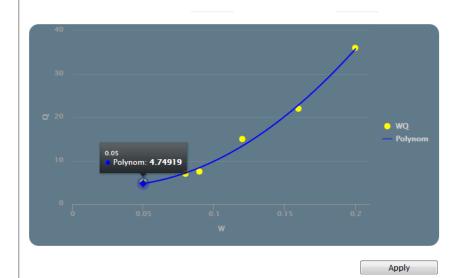
▷ Replacement

Behavior of replacement function

Setting

Description

○ from measurements (continued)



W-Q measurements

Then enter values for date and measuring values for W and corresponding Q in table below

□ active / delete

> ☑ Tick checkbox to activate or delete value pair for W/Q curve.

b Click **Add new measurement** to add new line to enter additional values.

b Click **Redraw** to save settings. Values are displayed in the list above.

Curve fitting options

The pairs of value are plotted in W/Q graph for rating curve according to approximation settings.

Fit:

▼ linear

polynomial 2nd

(...)

The values and the discharge rating curve are plotted in a W/Q diagram. For curve fitting choose linear or polynomials up to 6 degrees.

> Select reasonable curve fitting options from drop-down list.

W min / W max

> Enter minimum / maximum value for water level.

Q min / Q max

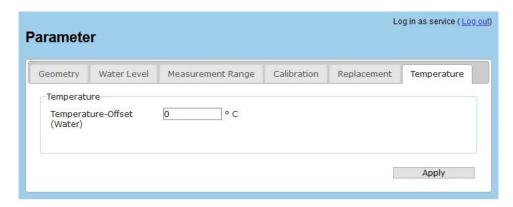
> Enter minimum / maximum value for discharge.

b Click **Apply** to redraw graph.

▷ Replacement **Behavior of replacement function** Setting Description > Tick checkbox for empirical discharge calculation according to **Manning** and enter ○ Manning corresponding parameters (see 11.1). Replacement function calculation: none from measurements Manning Manning Strickler from polynom Manning-Strickler coefficient MaxW: MinW: m Slope: n-factor: MaxW / MinW >Enter minimum / maximum value for water level. Slope > Enter value for channel slope. (dimensionless: $\Delta y / \Delta x$; see below) Δγ Δχ n-factor > Enter specific roughness coefficient n for channel material. (Manning Coefficient) ("Roughness Coefficients" on page 109) b Click **Apply** to save settings

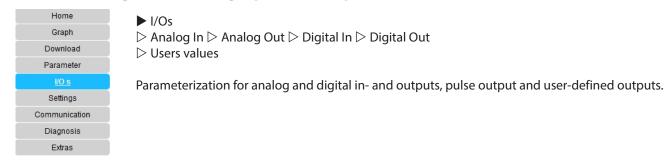
▷ Replacement	
Behavior of replacement	t function
Setting	Description
○ Manning Strickler	Description > Tick checkbox for empirical discharge calculation according to Manning Strickler and enter corresponding parameters ("Roughness Coefficients" on page 109). Replacement function calculation:
	MaxW / MinW > Enter minimum / maximum value for water level.
O Manning Strickler (continued)	Slope > Enter value for channel slope. (dimensionless: $\Delta y / \Delta x$; see below) $\Delta y \qquad \qquad \Delta x$
	kst-factor > Enter specific roughness coefficient kst for channel material. (Strickler Coefficient) ("Roughness Coefficients" on page 109)
	b Click Apply to save settings
O from polynom	> Tick checkbox to calculate discharge from polynom coefficients.
	Replacement function calculation: none from measurements Manning Manning Strickler from polynom Polynomcoefficents c0: 0.00028 c1: 0 c2: 0 c3: 0 c4: 0 c5: 0 c6: 0
Polynom-coefficients c0	> Enter coefficients of desired polynomial fitting / regression. b Click Apply to save settings.

7.7.6. Temperature



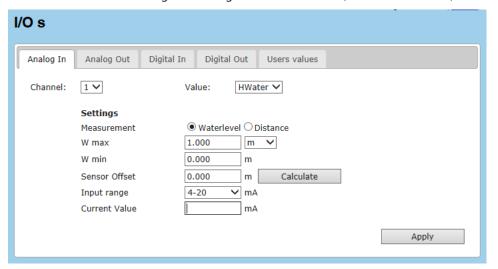
▶ Replacement		
Setting	Description	
Temperature-Offset	> Default setting: 0 °C. Enter the difference between a reference temperature measurement and	
(Water)	the integrated temperature measurement of the area velocity sensor.	
	Example: Tref = 20 °C and Tint = 19 °C; temperature offset = $+1$ °C	

7.8. I/Os – Digital and analog inputs and outputs



7.8.1. Analog Input

Parameterization and settings for analog connected sensors (water level sensors, sensors for user defined parameters).

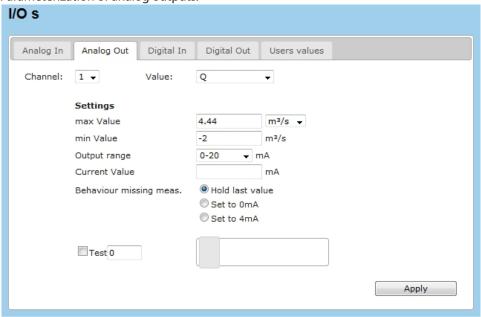


Setting	Description
Channel	Assignment of available channels for connected sensors.
▼ 1,2,3,4	> Select desired channel (analog input) from drop-down list.
Value	> Select the connected external water level sensor type for preselected channel from drop-down
▼ HWater,	list.
HAir,	
None	① Always connect the external water level sensor on channel 1.
	As value always choose HWater for channel 1.
	This water level sensor can be selected for discharge calculation in the main menu under
	► Parameter ▷ Water Level as H (Extern 1).
	HWater: External water level sensor connected on channel 1.
	HAir: If a second water level sensor is connected on channel 2, 3 or 4, then choose HAir as value.
	None: No analog sensor is connected.
Settings	
Measurement	Select the method of water level measurement (water level / distance).
Measurement	The sensor measures the water level from bottom to water surface
● Waterlevel	(height of water column).
	The user defined water level range of the selected sensor is proportional to the input current
	range.
	Example: 010 m water level measuring range
	0/4 mA corresponds to 0 m water level and 20 mA corresponds to 10 m water level
	NOTE: Choose this option for parameterization of all water level sensor types provided by the
	manufacturer. Even if non-contact sensors are used, the distance values are converted
	to water level values by the sensor.
W max	> Enter max. water level value for max. current input value:
	Example: water level measurement range 010 m:
	20 mA corresponds to 10 m water level
	Select corresponding unit for water level (length).
W min	>Enter min. water level value for min. current input value:
	0 mA corresponds to 0 m water level
	Select corresponding unit for water level (length).
Measurement	The water level sensor is mounted above water surface and measures the distance from sensor
● Distance	surface to the water surface. In this case, a high water level means a smaller distance to the
	sensor and vice versa.
	Example: distance measuring range 010 m:
	0 mA corresponds to 0 m distance (= 10 m water level)
	20 mA corresponds to 10 m distance (= 0 m water level)
max Distance	> Enter max. distance value for the min. current input value:
	Example for 010 m water level measuring range:
	0 mA corresponds to 10 m distance (= 0 m water level)
D'	Select corresponding unit for distance (length).
min Distance	> Define min. distance for max. current input value:
	20 mA corresponds to 0 m distance (=10 m water level)
	Select corresponding unit for distance (length).

Setting	Description
Sensor offset	Depending on the sensor position and orientation in the cross section, the measured water level value must be corrected by an off-set value to obtain correct readings. By entering the sensor offset, the measured water level value is automatically corrected by the offset value.
	Example: The water level sensor is installed 1.00 m below water surface and indicates $W = 1.00$ m. However, the water-level according to the gauge board = 1.05 m. Consequently, the offset value is 0.05 m and the water level value is corrected by 0.05 m.
	There are two options to obtain the offset value:
	Option 1: > Enter the offset value for the installed water level sensor (fix value). for example 0.05 m
	Sensor Offset 0.05 m Calculate
	Option 2: The offset value will be calculated by a reference measurement. The measured water level is compared internally with the reference water level (for example from reference device or staff gauge) and the corresponding is calculated and displayed.
	b Click Calculate.
	Sensor Offset 0.000 m Calculate
	Enter current water level value (measured by a reference device, staff gauge).
	Sensor offset *
	Please enter the current water level
	Update Cancel
	b Click Update to apply calculated offset value for measurement values or Cancel to abort.
Input range ▼ 420 020	> Select current input range in mA from drop-down menu.
Current value	Display of actual input current.
	b Click Apply to save settings.

7.8.2. Analog Output

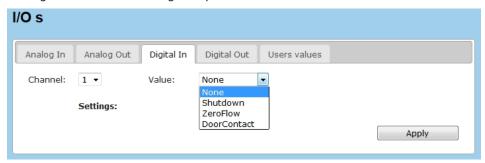
Parameterization of analog outputs.



Setting	Description		
Channel	Assignment of available channels.		
▼ 1,2,3,4	> Select desired channel (analog output) from drop-down list.		
Value	> Select measured value / parameter from drop-down list corresponding to channel; the		
▼ Q,	corresponding unit is displayed. (for example Q)		
A Settings			
Max Value	> Enter maximum for selected parameter.		
iviax value	Select corresponding unit.		
Min Value	> Enter minimum for selected parameter.		
Output range ▼ 420 020	> Select current output range in mA from drop-down menu.		
Current value	Display of actual output current.		
Behavior missing meas.	Choose between the following options in case of missing measuring values. O Hold last value Tick if exported value is missing. The last current/voltage is maintained.		
	⊙ Set to 0 mA		
	Measurement output value is set to 0 mA.		
	⊙ Set to 4 mA		
	Measurement output value is set to 4 mA.		
□ Test	> ☑ Tick checkbox to enable test.		
	Adjust test bar to different values.		
	♦ Click Apply to save settings.		

7.8.3. Digital Input

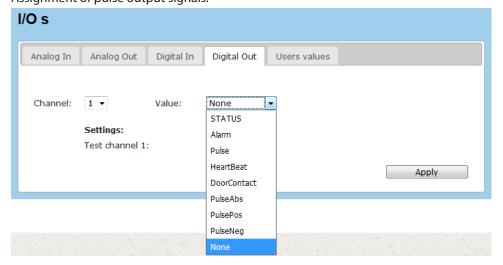
Settings for connection on digital input.



▷ Digital In				
Setting	Description			
Channel	Assignment of available channels.			
▼ 1,2	> Select channel for corresponding value from drop-down list.			
Value	> Select corresponding function for selected channel from drop-down list.			
▼ None	None: default setting, no signal			
Shutdown	Shutdown: system shutdown (reboot) after predefined delay time.			
ZeroFlow	ZeroFlow: during signal input discharge is set to "zero"			
DoorContact	DoorContact: This feature is visible, but not functional.			
Settings				
Delay	> Enter time (delay time) in s; after delay period the system reboots.			
(only applicable for "Shutdown")	δ Click Apply to save settings.			

7.8.4. Digital Output

Different signal types can be exported as digital output signals. Assignment of pulse output signals.



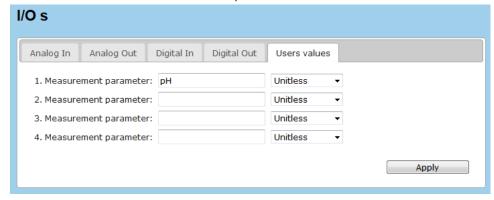
▷ Digital Out				
Setting	Description			
Channel ▼ 18	Available channels for assignment of values. > Select channel for corresponding value from drop-down list.			
Value ▼ STATUS Alarm Pulse HeartBeat DoorContact PulseAbs PulsePos PulseNeg None	> Select value from drop-down list to define alarm signal via relay for selected parameters.			
Value	> Select STATUS for export of error message			
▼ STATUS	The STATUS value corresponds in the software to a binary bit field where each bit reflects an information. With the help of a bit mask this information can be filtered out and exported through the digital output. > STATUS = Error codes (= bit mask)			
Settings				
	Channel: 1 ▼ Value: STATUS ▼			
	Settings:			
	Mask: 1			
	Delay: 0.5 s			
	Inverted:			
	Test channel 1:			
	Test value 1: Low ◎ ◎ High			
Mask	> Enter bit mask no. (currently 1 for bit mask error codes)			
Delay	> Enter time in s. Enter delay time in s between change of status and the setting of the digital			
las contro d	channel.			
Inverted	Option to invert digital output signal.			
	☑ Tick checkbox to invert signal.			
	Example:			
	Mask value is 1. If bit 0 is set in STATUS the output signal is not active (de-energized), if bit 0 in			
	STATUS is not set the output signal is active (energized).			
	☐ Output signal is not inverted.			
	Example:			
	Mask value is 1. If bit 0 is set in STATUS field the output signal is active (energized), if bit 0 is not			
	set in STATUS, the output signal is not active (de-energized).			
Test Channel 1	☑ Tick checkbox to activate signal test.			
Test value 1	Specify low or high signal.			
	⊙ low / ⊙ high			
	♦ Click Apply to save settings.			

	Description			
Setting	Description Assignment of auxillable phagmals			
Value ▼ Alarm	Assignment of available channels. > Select Alarm from drop down list to define alarm signal via relay for selected parameters.			
▼ Alarm	> Select Alam	n from drop dow	Thist to define alarm signal via relay for selected parameters.	
	Channel: 1	▼ Value:	Alarm ▼	
	Ent	tings		
		tings: asurement value:	Q	
	Limi		m³/s ▼	
	Тур		✓ above	
	Typ	C.	below	
	Hys	terese:		
	Dela	av:	s	
		t channel 1:		
		t value 1:	Low O O High	
Management				
Measurement value	> Select desir	ed parameter for	alarm signal from drop-down list.	
Limit	> Enter minin	num value (lower	limit) for alarm activation.	
Туре		activation above	or below set limit.	
	☑ above			
	Tick to trigger alarm above limit.			
	☑ below			
	Tick to trigger alarm below limit.			
Hysteresis	> Enter hysteresis value to define upper and lower limit which has to be exceeded to trigger an			
	alarm (limit ± hysteresis).			
	A suitable hysteresis value prevents the alarm from being triggered unnecessarily by small measurement deviations.			
Delay	> Enter minimum time span for measuring values exceeding the upper or lower limit. Only after			
Delay	this time an alarm is activated.			
	This option avoids that an alarm is activated due to short term deviations.			
Test Channel 1	<u> </u>			
Test value 1	☑ Tick checkbox to activate signal test. Specify low or high signal-			
iest value i	⊙ low / ⊙ high			
	♦ Click Apply to save settings.			
Value			nole for values acceptor (totalinor)	
Value			nals for volume counter (totalizer).	
▼ Dulco	4 types of counters (totalizer) can be parameterized taking into account the flow direction (positive +V in flow direction / negative -V against flow direction).			
▼ Pulse Pulse∆hs		II HOW direction /	ricquite v against now anection,	
PulseAbs	(positive +v i			
PulseAbs PulsePos		er ▶ Settinas ▷ 1		
PulseAbs		er ▶ Settings ▷ 1 Volume value	otalizer (7.9.4)	
PulseAbs PulsePos		Volume value	otalizer (7.9.4)	
PulseAbs PulsePos	See also unde	Volume value (+/- sign are ta	Totalizer (7.9.4) - difference	
PulseAbs PulsePos	See also unde	Volume value (+/- sign are ta	otalizer (7.9.4) - difference aken into account in summation of V) ne positive) -V (volume negative)	
PulseAbs PulsePos	See also unde	Volume value (+/- sign are to V = +V (volum Absolute volu (- sign of nega	Totalizer (7.9.4) - difference aken into account in summation of V) the positive) -V (volume negative) me tive volume is not taken into	
PulseAbs PulsePos	See also unde	Volume value (+/- sign are to V = +V (volume Absolute volue (- sign of negator) account in sur	Totalizer (7.9.4) - difference aken into account in summation of V) the positive) -V (volume negative) me utive volume is not taken into mmation)	
PulseAbs PulsePos	See also unde	Volume value (+/- sign are to V = +V (volume Absolute volute (- sign of negotian account in surue) V abs (absolute	Totalizer (7.9.4) - difference aken into account in summation of V) the positive) -V (volume negative) me utive volume is not taken into mmation) the volume) =	
PulseAbs PulsePos	See also unde	Volume value (+/- sign are ta V = +V (volum Absolute volu (- sign of nega account in sur V abs (absolut V (volume pos	Totalizer (7.9.4) - difference aken into account in summation of V) the positive) -V (volume negative) the positive volume is not taken into the mation) the volume) = sitive) + V (amount volume negative)	
PulseAbs PulsePos	See also unde	Volume value (+/- sign are ta V = +V (volum Absolute volu (- sign of nega account in sur V abs (absolut V (volume pos Total positive	Totalizer (7.9.4) - difference aken into account in summation of V) the positive) -V (volume negative) me titive volume is not taken into mmation) the volume) = sitive) + V (amount volume negative) volume (+V)	
PulseAbs PulsePos	See also unde Pulse: PulseAbs:	Volume value (+/- sign are to V = +V (volum Absolute volu (- sign of nega account in sur V abs (absolut V (volume pos Total positive (V against flov	Totalizer (7.9.4) - difference aken into account in summation of V) the positive) -V (volume negative) me tive volume is not taken into mmation) the volume) = sitive) + V (amount volume negative) volume (+V) v direction)	
PulseAbs PulsePos	See also unde Pulse: PulseAbs:	Volume value (+/- sign are to V = +V (volum Absolute volu (- sign of nega account in sur V abs (absolut V (volume pos Total positive (V against flow Total negative	Totalizer (7.9.4) - difference aken into account in summation of V) the positive) -V (volume negative) me tive volume is not taken into mmation) the volume) = sitive) + V (amount volume negative) volume (+V) v direction)	

▷ Digital Out				
Setting	Description			
Value ▼ Pulse PulseAbs PulsePos PulseNeg (continued)	Channel: 1 Value: Pulse Settings: Sum: Width: Test channel 1: Test value 1: Low High			
Sum:	> Select volume value to trigger pulse. (for example 50 m³: 1 pulse is triggered per 50 m³)			
Width:	> Enter value for pulse width. Default value: 500 ms			
Test Channel 1	☑ Tick checkbox to activate signal test.			
Test value 1	Specify low or high signal. ⊙ low / ⊙ high			
Value ▼ HeartBeat	 Click Apply to save settings. Select HeartBeat to monitor that system is running. (Every 30 s the system sends a ping/signal). 			
	Channel: 1 V Value: HeartBeat V Settings: Test channel 1: Test value 1: Low O O High			
Test Channel 1	☑ Tick checkbox to activate signal test.			
Test value 1	Specify low or high signal. ⊙ low / ⊙ high			
Value ▼ DoorContact	♦ Click Apply to save settings.This feature is visible but not functional.			
Test Channel 1	☑ Tick checkbox to activate signal test.			
Test value 1	Specify low or high signal ⊙ low / ⊙ high b Click Apply to save settings.			
Value ▼ None	> Select None for no further settings. Click Apply to save settings.			

7.8.5. Users Values

Definition of user defined measurement parameters for the connection of max. 4 additional sensors.



□ Users values				
Setting	Description			
1. Measurement parameter	> Enter measurement parameter and corresponding unit of additional connected sensor.			
2. Measurement parameter	> Enter measurement parameter and corresponding unit of additional connected sensor.			
3. Measurement parameter	> Enter measurement parameter and corresponding unit of additional connected sensor.			
4. Measurement parameter	> Enter measurement parameter and corresponding unit of additional connected sensor.			
	b Click Apply to save settings.			

7.9. Settings – Data Logging and Display



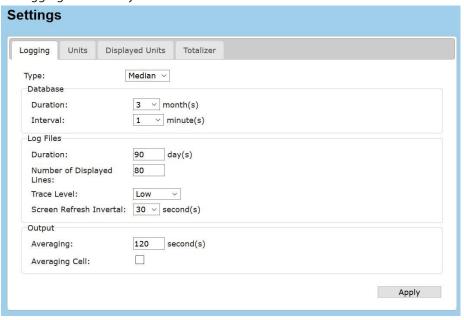
▶ Settings

□ Logging □ Units □ Displayed Units □ Totalizer

Settings for data logging and log-file logging, settings for displayed units, user defined units, settings for totalizer.

7.9.1. Logging

Specifications for data and log file logging. Note that log files contain important information for troubleshooting and debugging in case of system failure.



▷ Logging			
Setting	Description		
Type ▼ Mean Median	>Select type of average calculation for measuring values from drop-down menu.		
Database			
Duration ▼ 1, 2,, 11, 12	> Select time span for database history from drop-down menu.		
Interval	> Select time span for database interval from drop-down menu.		
Log Files			
Duration	> Enter time span after log file is deleted.		
Number of Displayed Lines	> Enter number lines of log file to be displayed.		
Trace Level ▼ Less Medium High	> Select trace level for display of log file content. For example Trace Level Less: log file contains less detailed information than log file Trace level High (Default: Less)		
Screen Refresh Interval ▼ 15, 30, 60	> Select time span for screen refresh from drop-down menu.		
Output			
Averaging	> Enter time span which will be used for averaging (mean or median).		
	① Time span should not be smaller than database interval.		
Averaging Cell	☐ Tick checkbox to average cells for data in database.		
	b Click Apply to save your entries.		

7.9.2. Units

Free user defined setting of units for the following parameters: discharge (Q)

- velocity (v)
- length (l)
- area (A)
- time (t)
- voltage (U)
- temperature (T)
- signal
- volume (V)
- concentration

Conversion factors of common measurement units are already specified. New units can be defined and added by the user.

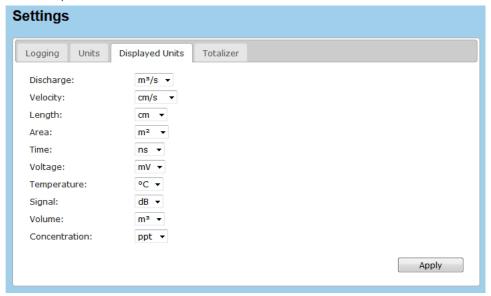


□ Units □ Units □ Definition of displayed unit for listed parameter.				
Discharge	reference unit:	m³/s	(cubic meters per second)	
	available units:	l/s m³/h Mld Gps Gpm Gph Gpd MGpd	(liter per second) (cubic meters per hour) (million liters per day) (US gallons per second) (US gallons per minute) (US gallons per hour) (US gallons per day) (million US gallons per day)	
Velocity	reference unit:	m/s	(meter per second)	
	available units:	km/h feet/s cm/s	(kilometer per hour) (feet per second) (centimeter per second)	
Length	reference unit:	m	(meter)	
	available units:	ft km mm cm	(feet) (kilometer) (millimeter) (centimeter)	

▽ Units				
Definition of displayed unit for listed parameter.				
Setting	Description			
Area	reference unit:	m ²	(cubic meter)	
	available units:	cm ²	(cubic centimeter)	
Time	reference unit:	S	(seconds)	
	available units:	m ms µs ns	(minutes) (milliseconds) (microseconds) (nanoseconds)	
Voltage	reference unit:	V	(Volt)	
	available units:	mV	(millivolt)	
Temperature	reference unit:	°C	(degrees Celcius)	
	available units:	°F	(degrees Fahrenheit)	
Signal	reference unit:	dB	(decibels)	
Volume	reference unit:	m³	(cubic meters)	
	available units:	I MI	(liter) (million liter)	
Concentration	reference unit:	ppt	(parts per trillion)	
	available units:	psu	(practical salinity unit)	
Unit	> Enter desired u	> Enter desired unit.		
Conversion	> Enter conversio	> Enter conversion factor related to reference unit.		
		δ Click Add to save selected unit.		
	♦ Click Delete to delete entry.			

7.9.3. Displayed Units

Choose specific measurement units for parameters to be displayed in graphs, input masks and data files (Download selectable).

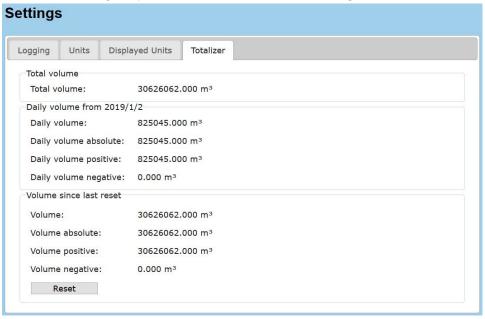


▷ Displayed Units		
Setting	Description	
Parameter Discharge Velocity Length Area Time Voltage Temperature Signal Volume Concentration	> Select desired unit from drop-down lists. Example: Drop-down list for units for discharge; Units to be defined under ▶ Settings ▷ Units	
Concentration	♦ Click Apply to save entries.	

7.9.4. Totalizer

Totalizer function for measurement and display of total and daily volume values (V). Flow is measured in either direction (bi-directional):

Volume positive +V (in flow direction), Volume negative -V (against flow direction) Set, define or change required unit for Volume under ▶ Settings ▷ Units.



▽ Totalizer		
Setting	Description	
Total volume		
Total Volume	Internal sum counter of total volume > Display of volume value measured since first system start / first commissioning. This value cannot be reset to zero.	
Daily volume from Y	YYY/MM/DD	
Daily volume	Daily volume counter (V difference) > Display of daily volume value +/- sign are taken into account in summation of V V (daily volume) = +V (volume positive) -V (volume negative)	
Daily volume absolute	> Display absolute volume per day (day total) (- sign of negative volume is <u>no</u> t taken into account!) V (daily volume absolute) = V (volume positive) + V (amount volume negative)	
Daily volume positive	Positive counter (+ V): > Display of daily volume <u>against</u> flow direction	
Daily volume negative	Negative counter (-V): > Display of daily volume <u>in</u> flow direction	
Volume since last reset		
Volume	Volume counter (V difference) > Display of volume value +/- sign are taken into account in summation of V V (daily volume) = +V (volume positive) -V (volume negative)	

▷ Totalizer		
Setting	Description	
Volume absolute	> Display absolute volume (- sign of negative volume is <u>no</u> t taken into account!) V (volume absolute) = V (volume positive) + V (amount volume negative)	
Volume positive	Positive counter: > Display of volume <u>against</u> flow direction	
Volume negative	Negative counter: > Display of volume <u>in</u> flow direction	
	& Click Reset to reset volume counters.	

7.10. Communication – Network Settings



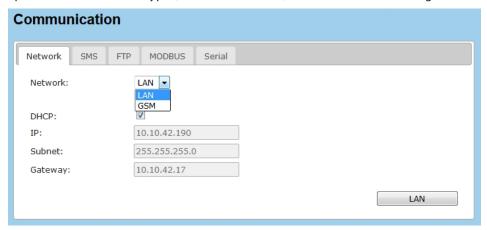
▶ Communication

 \triangleright Network \triangleright SMS \triangleright FTP \triangleright MODBUS \triangleright Serial

Settings for communication with transmitter and data transfer; settings for SMS notification.

7.10.1. Network

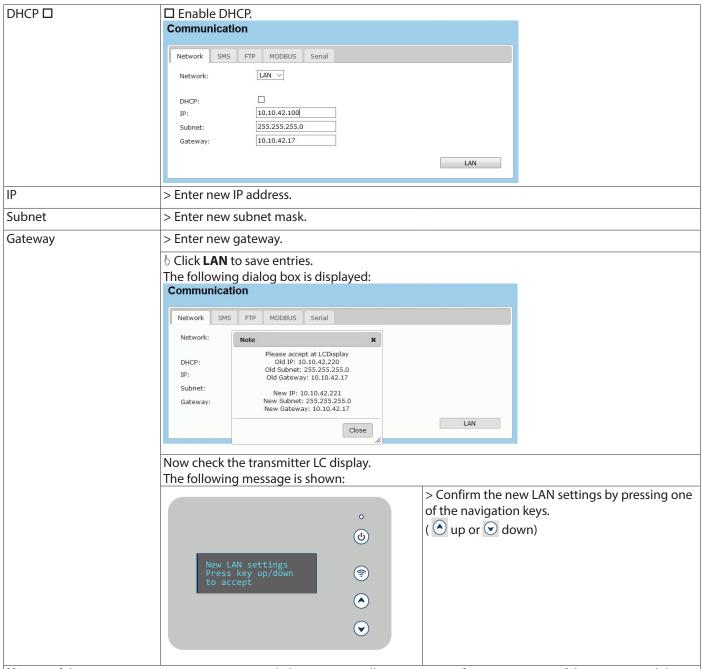
Specification of network type (LAN or GSM/WLAN) and basic network settings.



Network: ▼ LAN GSM	> Select network type from drop-down list. ▼ LAN
Setting	Description
DHCP ☑	☑ Enable / ☐ disable DHCP
	> ☑ DHCP (Dynamic Host Configuration Protocol) enabled. (factory setting) DHCP is activated and the IP address, Subnet and Gateway are automatically assigned by the server.
IP	Display IP address (automatically assigned).
Subnet	Display subnet mask (automatically assigned).
Gateway	Display gateway address (automatically assigned). b Click LAN to confirm entry.

7.10.1.1. Manual Input and Changing the IP Address

If a static IP address is required (for example if no DCHP server is available) the network parameters can be assigned manually. Change the following settings:



NOTE: If the new LAN settings are not accepted, the message will appear again after every restart of the system until the settings are confirmed by pressing a navigation key.

Gateway (continued)



After pressing a navigation key, the new LAN settings are displayed.

NOTE: Note that the existing network connection is disconnected automatically after the settings have been changed! Run your web browser again and enter the new IP address in the address bar to reconnect again.

GSM network

Network:	> Select network type GSM from drop-down list for communication via GSM network.
▼ LAN	▼ GSM
GSM	

NOTE: Note that the settings for GSM network vary according to the device and communication type:

Device with external 3G/2G router:

When using an external 3G/2G router, no settings are required at this point. The router configuration is carried out via an integrated web interface. An additional router configuration manual will be provided to make sure correct connection and configuration.

Device with integrated 4G/3G/2G modem:

When using the integrated option, note that the modem is completely preconfigured by the manufacturer. Settings can be checked under the menu point Modem configuration via the modem user interface (see under "GSM network settings for IS-6000 Doppler with integrated 4G/3G/2G modem" on the following pages).

GSM network Communication settings for Network SMS FTP MODBUS Serial IS-6000 Dopplerstandard type GSM ✔ (without 3G/2G router or GSM: 4G/3G/2G modem) Access Point Name: internet.t-mobile.de User: t-mobile Password: *99# Number: GSM IP: No Connection Signal strength: GSM Access data for log-in are obtained form the service/network provider. Access Point Name > Enter Access Point Name APN of service/network provider. User > Enter user name. Password > Enter password. Number > Enter dial-up phone number of service/network provider. **GSM IP** > Enter GSM IP. b Click **GSM** to save your entries. The IP address is displayed after successful login.

GSM network settings for IS-6000 Doppler with integrated 4G/3G/2G modem

> Select network type GSM from drop-down list for communication via GSM network.

▼ GSM

Integrated 4G/3G/2G modem:

For network settings only GSM type is needed (see below).

(i) Note that upon delivery, the integrated 4G/3G/2G modem is already pre-configured by the manufacturer. Just connect the dipole-antenna on the bottom of the enclosure and insert the SIM card to automatically connect to your provider.



① Note that APN, username and password are given by the network provider of the SIM Card (network profile).

To avoid possible misconfigurations, do not change parameters. Change settings only if you have the appropriate experience.

Modem Configuration

To check or change the settings of the configuration

b Click **Modem Configuration**

GSM Config

The WebUI interface of the original modem manufacturer opens.

The functions are described in the following.

(i) Note that the configuration is saved when the "Save" button is clicked, and the configuration is applied at the next system boot.

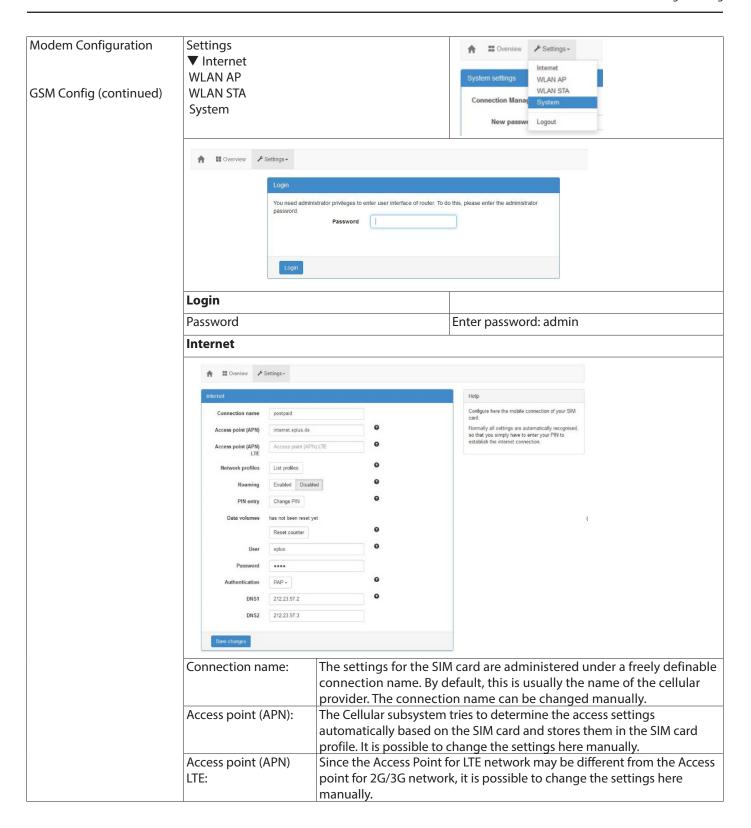
Overview

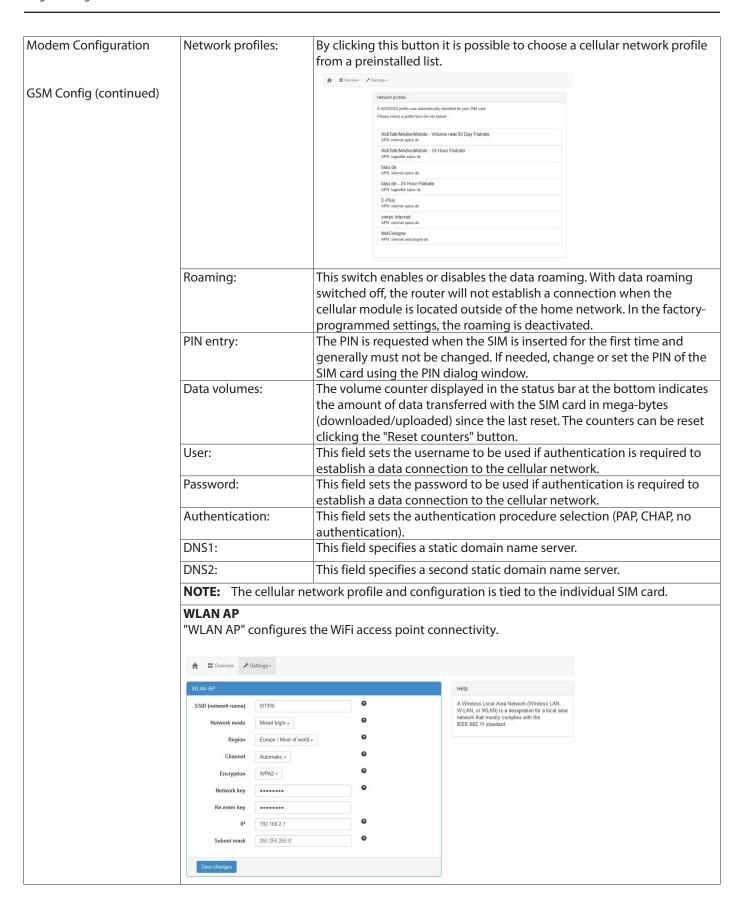
Information regarding the cellular connectivity is displayed.

bottom left: display of current GSM connectivity



Internet	
Connection	
Internet IP	IP address assigned by provider
SIM profile	Profile name
Roaming	deactivated (factory setting / default setting)
WLAN AP	
Connection	
Router IP	IP address network
Network name	SSID of the WiFI access point
Encryption	Encryption WiFi access point





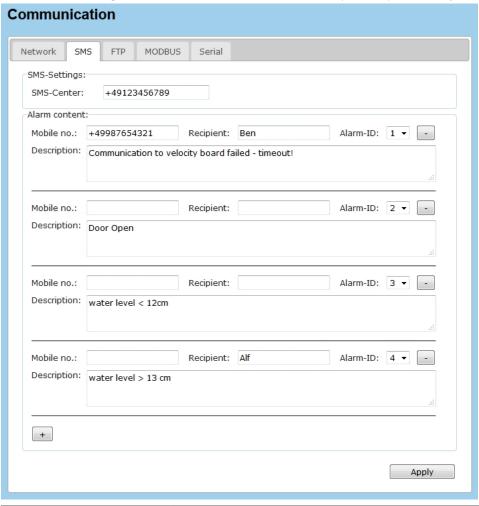
	SSID (Network name):	This field determines the SSID of the WiFi
	N	access point. The factory-programmed value is "UBXWifi".
SCALC C /	Network mode:	The network mode determines the IEEE 802.11 standard of the WiFi
GSM Config (continued)	D :	network. The factory-programmed value is "Mixed b/g/n".
	Region:	This field determines the regulatory domain. Depending on the region,
		specific channels are faded in or hidden. The factory-programmed value
	Cl. I	depends on the TOBY-L2 module version.
	Channel:	This field determines the channel of the WiFi access point. The factory-
	E C	programmed value is "Automatic".
	Encryption:	This field determines the encryption of the WiFi access point. The
	National Land	factory-programmed value is "WPA2".
	Network key:	This field is used to define the WPA/WPA2 key. The factory-programmed
	Da antaulaan	value is "ubx-wifi". The key must be suitable for the encryption method.
	Re-enter key:	This field is used for confirming the network key to prevent
	ID.	incorrect entries. This field determines the IP address of the
	IP:	
		WiFi access point.
	Subnet mask:	The factory-programmed value is "192.168.2.1".
	Subnet mask:	Subnet mask: This field determines the subnet mask of the WiFi
		access point.
		TI (, , , , , , , , , , , , , , , , , ,
		The factory-programmed value is: "255.255.255.0".
	WLAN STA	
	"WLAN STA" configures	s the connectivity to an external hotspot.
	Enable "WLAN STA". (ST	A mode enable : on)
		not operated as access point but as client!
		,
	↑ ■ Overview Settings -	
	WLAN STA	Help
	STA mode enable On Off	A Wireless Local Area Network (Wireless LAN, W-LAN, or VVLAN) is a designation for a local area
		network that mostly complies with the IEEE-802.11 standard.
	Save changes	
	System	
	-	
		voral system configurations
	System is used for se	veral system configurations.
	⇒ ■ Overview → Settings -	veral system configurations.
	↑ # Overview Settings -	
	♠ ■ Overview ✓ Settings System settings	Help
	↑ # Overview Settings -	
	System settings Connection On Off	Help Change various system settings such as default homepage, system password
	System settings Connection On Off Manager	Help Change various system settings such as default homepage, system password or protection.
	System settings Connection On Off Managor New password New password	Help Change various system settings such as default homepage, system password or protection.
	System settings Connection On Off Managor New password Repeat password Password Settings	Help Change various system settings such as default homepage, system password or protection.
	System settings Connection	Help Change various system settings such as default homepage, system password or protection.
	System settings Connection On Off Manager New password Repeat password Repeat password Password Password Password Language English	Help Change various system settings such as default homepage, system password or protection. All pages
	System settings Connection	Help Change various system settings such as default homepage, system password or protection. All pages
	System settings Connection Managor New password Repeat password Password	Help Change various system settings such as default homepage, system password or protection.
	System settings Connection	Help Change various system settings such as default homepage, system password or protection.
	System settings Connection	Help Change various system settings such as default homepage, system password or protection.

Modem Configuration	New password:	This field is used to change the system password.
	Repeat password:	This field is used for confirming the system password to prevent incorrect entries.
GSM Config (continued)	Password protection:	This switch determines the protection level of web pages. If the "Settings page" option is set, then the WiFi / Cellular subsystem router will only ask for a password when entering the settings page. On the other hand, if the "All pages" option is selected, then all the tabs of the WiFi / Cellular subsystem web interface will be password protected.
	Language:	This multiple choice switch is used to select the output language of the WebUI.
	Reset device:	The "System reset" button reboots the WiFi / Cellular subsystem router, while the "Factory reset" button resets the WiFi / Cellular subsystem to the factory-programmed values.
	Web page FTP access:	The switch enables or disables the FTP access to the Web page files. The customer is allowed to personalize the aspect of the WebUI. The WebUI aspect may be reverted via AT command.

7.10.2. SMS

Settings for SMS alarm.

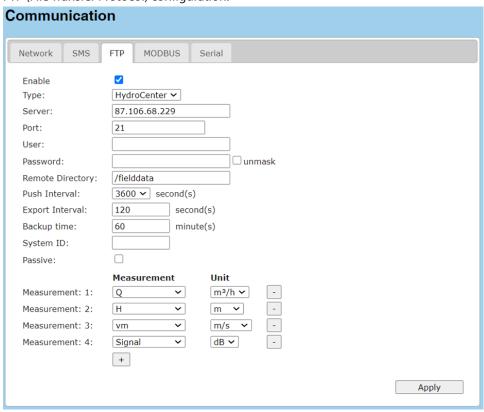
NOTE: The sending time of an SMS from the sender to a recipient depends solely on the service provider of the SMS Center.



⊳ SMS		
Setting Description		
SMS Settings		
SMS-Center > Enter service number of SMS center of the provider of your SIM card for forwarding SMS your mobile phone. (format: +49123456789; +country code mobile no.)		
Alarm content		
Mobile no.	> Enter mobile no. of recipient (+49128947662)	
Recipient	> Enter name of SMS recipient.	
Alarm ID	> Select alarm type (18) which is defined by the assignment of the respective digital output.	
Description	> Description of SMS alarm type (for example door open)	
+ -	> click + to insert new line (new alarm type) click - to delete line, alarm type.	
	b Click Apply to save entries.	

7.10.3. FTP

FTP (File Transfer Protocol) configuration.



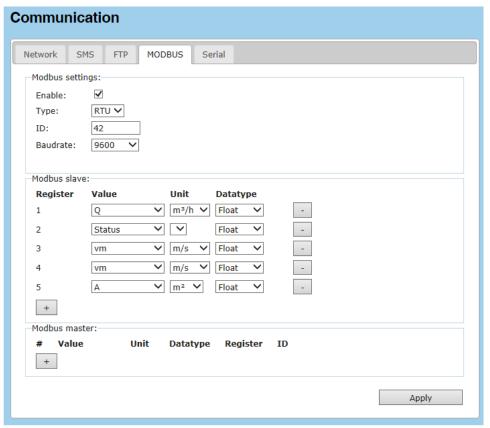
⊳ FTP		
Setting	Description	
Enable □	> ☑ Tick checkbox to enable / disable FTP.	
Server	> Enter server IP address. Do not enter a name!	
Port	> Enter port number.	
User	> Enter username.	
Password	> Enter password.	
Remote Directory	> Enter directory name on server.	
Push Interval ▼ 3600 () 300	> Select interval for file push. unit: s (seconds)	
Export Interval	> Data interval in file.	
Backup time	> Enter time span for the temporary data storage until the next data transmission.	
Remote Directory	> Enter directory name on server.	
System ID	> Enter system ID.	
Suffix ③ only for type Ott binary and XRZP	> Enter file extension (for example .csv)	
Passive	> ☑ Tick checkbox to enable FTP passive modus.	

▶ FTP	
Setting	Description
Measurement 1: Measurement Value: ▼ None A H ()	Specify measured values (Measurement 1) for data transfer. > Select measured values / parameters from drop-down list; corresponding units are displayed. (Explanation of abbreviations see 7.13)
▼ Unit	Display of corresponding units.
+ -	> Click + to add row for additional measurement value or – to delete values.
	& Click Apply to save entries.

7.10.4. Modbus

Modbus is a client-server communication protocol used for communication between electronic devices to exchange data mainly in the industrial environment.

A Modbus RTU interface (RS485/RS232) or an Ethernet interface with Modbus TCP protocol are available for communication.



⊳ MODBUS		
Setting	Description	
Modbus Settings		
Enable 🗆	> ☑ Tick checkbox to enable / disable Modbus.	
Type ▼ TCP RTU	> Select Modbus TCP or RTU protocol type from drop-down list.	
Type ▼ TCP	> Select TCP Modbus settings: Enable: Type: TCP Port: 9000	
Port	> 9000 (Default setting) TCP port number used for Modbus TCP server protocol.	
Type ▼ RTU	> Select Modbus RTU protocol type for data transmission via internal interface RS485/RS232. Modbus settings: Enable: Type: RTU ID: 42 Baudrate: 9600 Total Protocol type for data transmission via internal interface RS485/RS232.	
ID	> Enter device / flow meter identification number (modbus address).	
Baud rate ▼ 115200 () 1200	> Select desired baud rate from drop-down list.	
Modbus slave	Definition of data transfer if system is used as slave.	
Register 1, 2,	Number of register.	
Value ▼ None A ()	> Specify parameter for selected register.	
Units ▼	Display of corresponding units. > Select desired unit from drop-down menu.	
Datatype ▼ Float, LongInt	> Select data transmission format from drop-down list.	
+ -	> Click + to add row for additional register or – to delete register.	
Modbus master	Definition of data transfer if system is used as master.	
#	Line number.	
Value ▼ None A ()	> Specify parameter for selected line.	

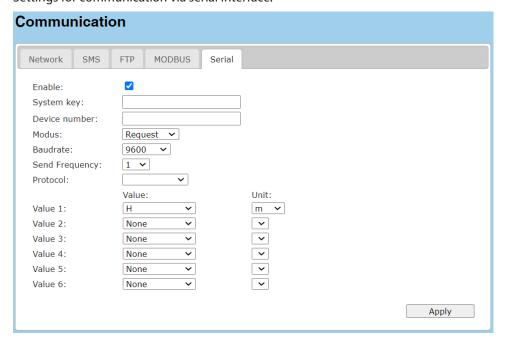
⊳ MODBUS	
Setting	Description
Modbus Settings	
Unit ▼	Display of corresponding units. > Select desired unit from drop-down menu.
Datatype ▼ Float, LongInt	> Select data transmission format from drop-down list.
Register	> Enter register.
ID	> Enter device / flow meter identification number (modbus address).
+ -	> Click + to add row for additional parameter or – to delete parameter.
	b Click Apply to save entries.
Further transmission	parameters for Modbus RTU protocol:
Data bits:	8
Stop bits:	1
Parity:	none
Realized functions:	Read holding register: Function 03

NOTE: If no measurement values are available (for example in case of missing values due to sensor failure), the following values are exported to Modbus interface:

- Maximum value for "Float" data type FLT_MAX = 3.4028234663852886e+38
- Maximum value for "LongInt" data type LONG_MAX = 2147483647

7.10.5. Serial

Settings for communication via serial interface.



▷ Serial	
Setting	Description
Enable 🗆	> ☑ Tick checkbox to enable / disable serial communication.
System key	> Enter system key.
Device number	> Enter serial number of device.
Modus ▼ Request Autosend	> Select the transfer mode.
Baud rate ▼ 115200 () 1200	> Select desired baud rate from drop-down list.
Send Frequency ▼ 1, 5, (), 60	> Select time span in seconds.
Protocol ▼ GWFSerial C Type SHWP	> Select serial communication protocol type. GWFSerial (Settings: baud rate 9600, parity: none; data bits: 8; stop bits 1) C Type Specific communication protocol corresponding to manufacturer specific data logger type. SHWP Specific communication protocol corresponding to manufacturer specific data logger type. Further specifications will be available on request.
Value ▼ A ()	> Specify output parameter from dropdown list.
Unit	> Select desired unit for the value.
▼	b Click Apply to save settings

Example: Request of a floating point value

The flow meter device has the modbus address 42 (ID: 42).

In the user interface in register 1 the device is exporting the parameter water level (H),

with current value 0.8351314 m (Register: 1, Value: H, Unit: m).

Request (hexadecimal): 2A 03 00 00 00 02 C2 10

Description	Hexadecimal byte	Remark
Address	2A	User settings – 42
Function	03	Read Holding Register
Start address high	00	Start address 0 (user settings Register 1)
Start address low	00	_
Number of values high	00	2 registers needed to represent a float
Number of values low	02	_
Error check CRC	C2 10	_

Answer (hexadecimal): 2A 03 04 CB 2C 3F 55 4F 13

Description	Hexadecimal	Remark
Address	2A	User settings – 42
Function	03	Read Holding Register
Byte counter	04	_
Data	CB 2C 3F 55	Value decimal = 0.8351314
		Value Hex (IEEE 754
		single precision) = 3F55CB2C
Error check CRC	4F 13 10	_

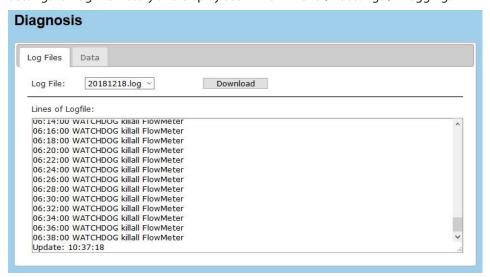
7.11. Diagnosis



7.11.1. Log Files

Diagnosis tool with display of log files. The log file contains the protocol with information, warnings and error messages of all operations the system has executed. It provides valuable information about possible errors in hardware and also errors resulting from incorrect operation by the user.

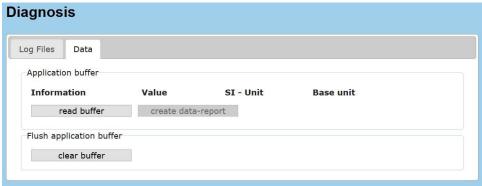
Settings for log-file history and display see in main menu ▶ Settings ▷ Logging.

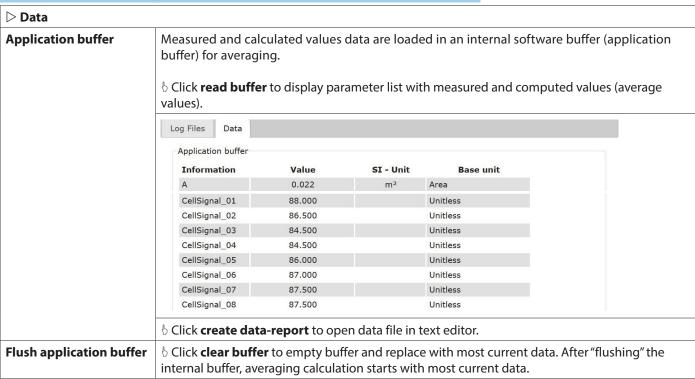


Dog Files	
Setting	Description
Log File	> Select log-file from drop-down list. Filename: yyyymmdd.log
	b Click Download to display file content.

7.11.2. Data

Display of parameter list with measured and computed values, conversion factors and corresponding units.





7.12. Extras

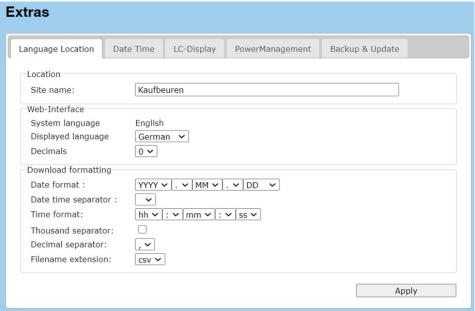


► Extras

- □ Language Location □ Date Time □ LC-Display

7.12.1. Language and Location

Language selection, site name entry field, settings for file, date, separator format.



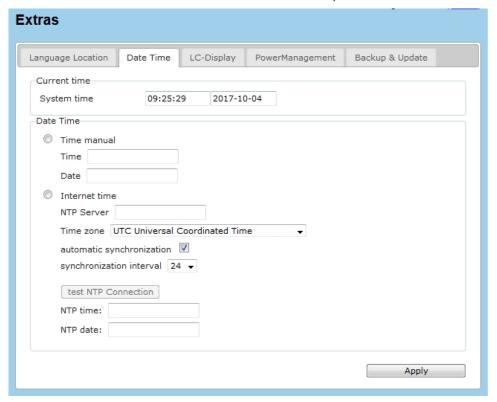
▶ Language Location		
Setting	Description	
Location		
Site name:	Enter name of measuring site.	
Web-Interface		
System Language	English	
Displayed language ▼ Spanish German Polish Japanese French Russian Czech	> Choose GUI display language. ⟨ Click Apply save data. The corresponding flag symbol of the selected language will be displayed. ⟨ Click the flag symbol to change between languages.	
Download formatting	① Download formatting is only possible for selectable download. Direct and monthly download cannot be formatted by user.	
Date format:	> Choose date format from drop down list.	
Date time separator	> Choose date and time separator from drop down list.	
Time format	> Choose time format from drop down list.	
Thousand separator	> ☑ Tick checkbox to insert decimal separator.	
Decimal separator	> Choose type decimal separator from drop down list.	

▶ Language Location	
Setting	Description
Filename extension	> Define file format (*.txt or *.csv) from drop down list.
	① Note that Excel might not open CSV files properly, for example all data are displayed in the first column due to different separators set in your Windows regional and language settings and the csv file. For easy and correct import of measuring data in Excel, we recommend to save data as text file (*.txt). Opening a txt- file will start the text import wizard. The dialog box makes sure correct data import by defining the delimiters for example for date, time.
	♦ Click Apply save data.

7.12.2. Date Time

Settings for time and date and option for time synchronization via internet.

Time synchronization via NTP server can be activated to synchronize the system time of the measuring system or PC with other data bases or networks to enable identical time stamps.



IMPORTANT

Save all measurement data (see chapter 7.6.1) and log files (see chapter 7.11.1) before changing system time or date. Otherwise, data could be deleted or overwritten. Measurement data and log files will be deleted if the last change to a file is too long in the past. The accepted time limit is 12 months for measurement data and 90 days for log files.

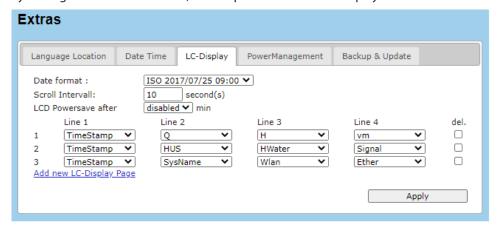
Date Time	
Setting	Description
Current time	
System time	> Display of current system time and date.
Date Time	
⊙ Time manual	 ◆ Check radio button to set time and date manually. After checking the button, the current time and date are displayed. ♦ Click on the respective input field to change the time and date Time > Set desired time Date > Enter desired date
	b Click Apply to save entries.
⊙ Internet time	⊙ Check radio button to activate time and date setting via NTP server (Network Time Protocol) Server.
	$\textcircled{\textbf{:}}$ NTP uses UTC (Coordinated Universal Time) for synchronization. In Germany MEZ (= CET) and MESZ (= CEST) is applied; CET = UTC + 1h respectively CEST = UTC + 2h

▷ Date Time	
Setting	Description
NTP Server	> Enter IP address of desired NTP Server.
	③Many lists of IP addresses of NTV servers are available online.
Time zone	> Select local time zone from drop-down list.
automatic Synchronization	> ☑ Tick check-box for automatic synchronization.
Synchronization interval	> Select desired interval for time synchronization from drop-down-list
Test NTP connection	b Click test NTP connection to check settings. NTP time & date are displayed.
	b Click Apply to save entries.

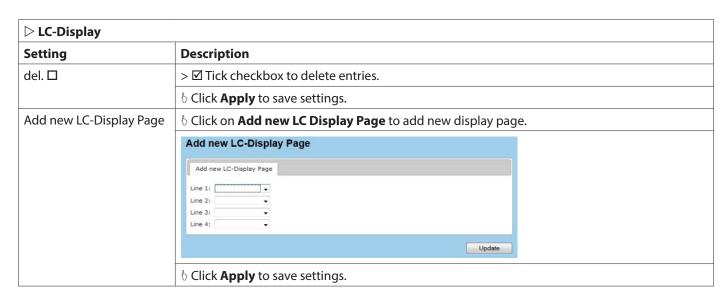
7.12.3. LC Display

Settings for LC- transmitter display.

Definition for displayed parameters for 4-line display of transmitter (Line 1...Line 4). 4 parameters per LC screen can be displayed at once. Parameters can be selected individually from parameter list (see "7.13. Abbreviations" on page 100). By adding additional LC screens, further parameters can be displayed in intervals.



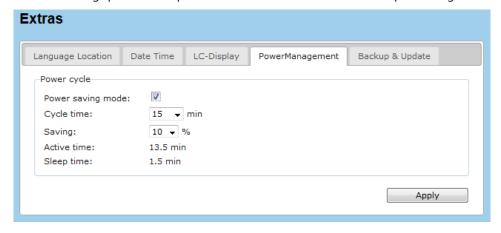
▷ LC-Display	
Setting	Description
Date format:	> Select data format. ISO: yyyy/mm/dd hh:ss US: mm/dd/yyyy hh:ss AM/PM
Scroll Interval	> Set time for scroll / display interval.
LCD Powersave after	> Set time for activation of power save modus for LC display. Or choose disabled to deactivate power save modus.
Line 1 Line 2 Line 3	> Select parameter to be displayed from drop-down list. (abbreviation of parameter names as listed in database)
Line 4	▼ TimeStamp Wlan () vm



7.12.4. Power Management

Settings for power saving options during battery operation to save energy and to extend battery life.

NOTE: During specified sleep time NO measurements and NO data processing are carried out.



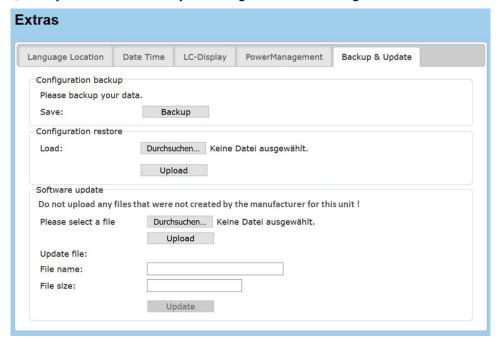
▷ Power Management		
Power cycle	Power cycle	
Setting	Description	
Power saving mode	> ☑ Tick checkbox to activate the power saving mode.	
Cycle time ▼ 15 30 () 360	> Select cycle time from drop-down list (max. 360 minutes). (Cycle time = Active Time + Sleep time)	
Saving ▼ 10 25 50 75 90	> Select requested percentage energy saving during set cycle time.	
Active time	Display of calculated active time during set cycle duration.	

Power Manage	ment
Power cycle	
Setting	Description
Sleep time	Display of calculated sleep time during set cycle duration.
	 Always check sleep time settings with settings for FTP configuration under ▶ Communication ▷ FTP.

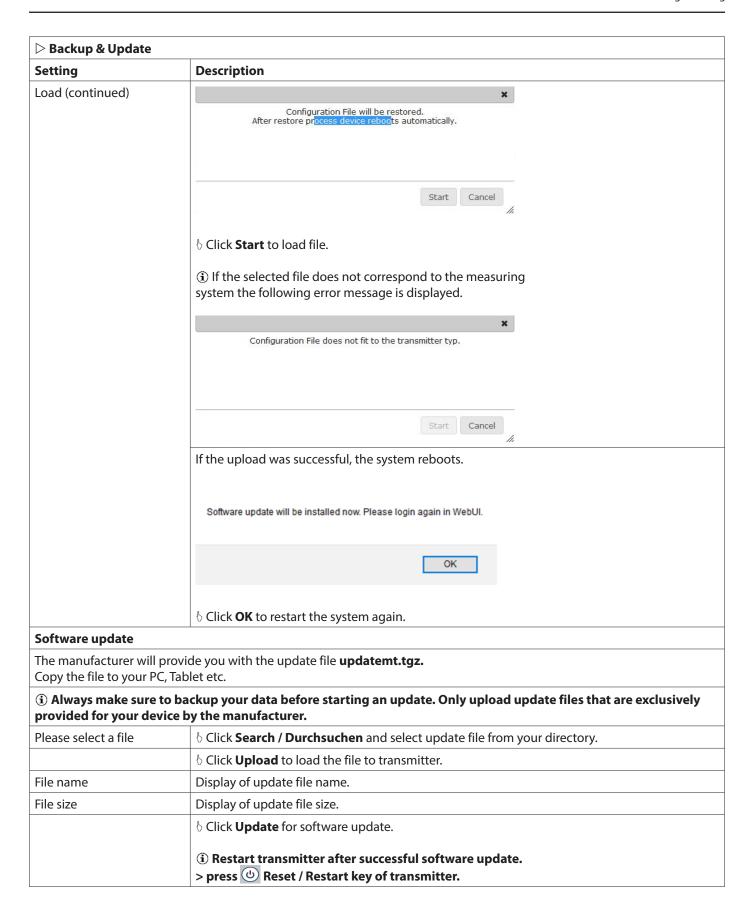
7.12.5. Backup & Update

Function to save and upload data of hardware configuration and measurement parameters and software update option. For a software update the manufacturer will provide you with the specific update file (updatemt.tgz).

(i) Always make sure to save your configuration and settings after initial commissioning of the device!



⊳ Backup & Upo	late
Setting	Description
Configuration b	ackup
Save	b Click Backup to save configuration file in txt format.
Configuration re	store
Load	b Click Search / Durchsuchen and select configuration file from your directory.
	♦ Click Upload to load file.



7.13. Abbreviations

NOTE: Display of parameters may vary according to the connected flow meter type.

(Parameter list under ▶ Diagnosis ▷ Data)

Abbreviation	Explanation
A	cross section area of flow
CellSignal_01 CellSignal_18	signal strength of single measuring cells (for example CellSignal_01: signal strength in cell 01)
DVol	daily volume
DVolAbs	daily volume absolute
DVolNeg	daily volume negative (negative flow direction)
DVolPos	daily volume positive (positive flow direction)
Н	water level, total
HAir	water level (external ultrasonic down-looking level sensor
HUS	water level (area velocity sensor)
HWater	water level (external hydrostatic level sensor)
OpHCount	operation time in hours
Q	discharge, flow
Status	status message of measuring system (only for internal use)
Salinity	salinity
Signal	signal strength
TAir	air temperature measured with additional external temperature sensor
TS	Timestamp
TWater	water temperature measured with additional external temperature sensor
TotalVolume	total volume
Volume	volume – since last volume reset
VolumeAbs	volume absolute – since last volume reset
VolumeNeg	volume negative (negative flow direction) – since last volume reset
VolumePos	volume positive (positive flow direction) – since last volume reset
V	velocity
vCell_01 vCell_19	mean velocity in single cell (for example vCell_01: velocity in cell 01)
vm	mean velocity
Parameter list for transmitter L	CD display
TimeStamp	current time
Wlan	active connection via WLAN
Ether	active connection via Ethernet / LAN
SysName	display of system name
Location	display of name of measuring site
CPUF	processor frequency
Text>	display text

8. SERVICE

8.1. Cleaning, Maintenance and Care

AWARNING

RISK OF ELECTRIC SHOCK!

ALWAYS DISCONNECT POWER BEFORE DISMOUNTING OR CLEANING THE TRANSMITTER AND THE SENSORS.

DO NOT USE ANY SHARP OR POINTED OBJECTS TO CLEAN THE SENSORS.

IF THE FLOW METER IS USED PROPERLY, NO SPECIAL MAINTENANCE IS REQUIRED IN NORMAL OPERATION.

NEVERTHELESS, CHECK TRANSMITTER, SENSORS, CABLES AND CONNECTIONS ON VISIBLE DIRT OR DEPOSITS AND DAMAGES. REMOVE POSSIBLE COATINGS AND DEPOSITS VERY CAREFULLY WITH A DAMP CLOTH AND MILD DETERGENT.

AWARNING

BIOLOGICAL HAZARD!

OBEY SAFETY REGULATIONS AND WEAR PERSONAL PROTECTIVE EQUIPMENT WHEN HANDLING A DEVICE THAT MAY HAVE COME IN CONTACT WITH BIOLOGICAL HAZARDOUS MATERIAL (FOR EXAMPLE, WASTEWATER). WASH AND DECONTAMINATE THE INSTRUMENTS (TRANSMITTER CASE, SENSORS, CABLES) WITH DISINFECTANT SOAP AND RINSE WITH WARM WATER BEFORE MAINTENANCE OR SHIPPING.

If the flow meter is used properly, no special maintenance is required in normal operation. The transmitter is designed to be practically maintenance and wear-free. Nevertheless, check transmitter, sensors, cables and connections on visible dirt or deposits and damages.

If necessary, the transmitter housing can be cleaned with a dry, dust- and lint-free cloth. In case of severe soiling, it can be wiped with a damp cloth.

Possible coatings and deposits on the sensors can be removed very carefully with a damp cloth and mild detergent.

8.2. Troubleshooting

8.2.1. Error Codes

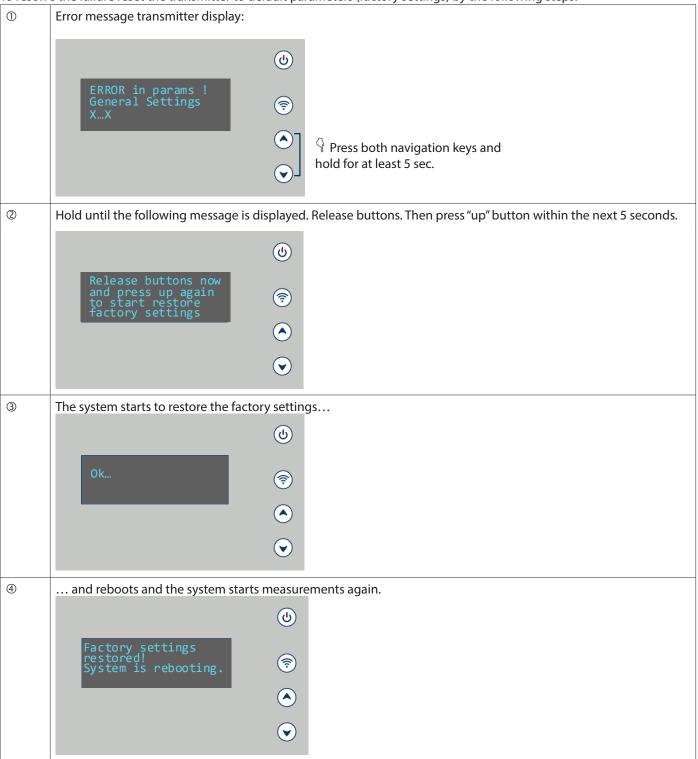
Error code	Error message	Description	Error Handling
1	failure	General system failure	Contact manufacturer
2	velocity	Failure velocity measurement	Check sensor and wiring
4	w water	Failure water level measurement with hydrostatic level sensor	Check sensor and wiring
8	w air	Failure water level measurement with ultrasonic down-looking level sensor	Check sensor and wiring
16	t water	Failure water temperature measurement (external T sensor)	Check sensor and wiring
32	t air	Failure air temperature measurement (external T sensor)	Check sensor and wiring
64	water level	Failure water level measurement	Check sensor and wiring
128	v sensor communication timeout	Failure communication / connection to velocity sensor	Check sensor and wiring

Table 1: Error codes (depending on the configuration of the measuring system)

8.2.2. Reset to Factory Settings

A total system failure might be caused by loss of the params.txt-file.

To resolve the failure reset the transmitter to default parameters (factory settings) by the following steps:



(5) After successful rebooting, it is now possible to upload the user-defined params.txt-file. Therefore Change to GUI and go to ▼ Extras ▷ Backup & Update: **Extras** Language Location Date Time LC-Display PowerManagement Backup & Update Configuration backup Please backup your data. Save: Backup Configuration restore Load: Durchsuchen... Keine Datei ausgewählt. Upload Software update Do not upload any files that were not created by the manufacturer for this unit !Please select a file Durchsuchen... Keine Datei ausgewählt. Upload Update file: File name: File size: Update **Configuration restore** b Click **Search / Durchsuchen** and select configuration file from your directory. b Click **Upload** to load file to transmitter. b Click **Start** to restore configuration file. 6 Now press Reset / Restart button of transmitter to restart again and to activate changed settings.

8.3. Return / Repair

Please follow the following instructions in case the device has to be returned to the manufacturer for repair or inspection. For returning the device proceed as follows:

- Request "Flow Meter Instrument Return Form" (IRF) by email from the manufacturer.
- Fill in one sheet per returned instrument. This will help us to get the information needed to carry out the repair as soon as possible.
- Include the completed and signed IFR with your return shipment.
- Clean and decontaminate the device properly.
- · Pack it safely by ideally using the original packing.
- Send the parcel to the manufacturer for repair

IMPORTANT

Keep original packaging for safe storage and safe transport.

ACAUTION

DECONTAMINATION NOTE

BECAUSE OF LEGAL REGULATIONS ON ENVIRONMENTAL PROTECTION AND FOR THE SAFETY AND HEALTH OF OUR EMPLOYEES, ONLY SEND BACK CLEAN AND DECONTAMINATED DEVICES. IF THE DEVICE HAS BEEN OPERATED WITH TOXIC, FLAMMABLE OR WATER-ENDANGERING PRODUCTS CHECK AND MAKE SURE, IF NECESSARY, BY RINSING OR NEUTRALIZING, THAT ALL CAVITIES ARE FREE FROM SUCH DANGEROUS SUBSTANCES. THE MANUFACTURER RESERVES THE RIGHT TO REFUSE THE DELIVERY OF DIRTY OR CONTAMINATED DEVICES OR, IF NECESSARY, CHARGE EXTRA CLEANING COSTS. SIGN THE IRF (INSTRUMENT RETURN FORM) TO CONFIRM THAT THE DEVICE IS SAFE TO HANDLE.

8.4. Disposal

AWARNING

DISCONNECT POWER BEFORE DISMOUNTING THE DEVICE.

RISK OF POTENTIAL HAZARD TO HUMANS AND ENVIRONMENT DUE TO HARMFUL SUBSTANCES. MAKE SURE, THAT THE DEVICE AND SENSORS ARE FREE FROM HARMFUL SUBSTANCES.

IMPORTANT

Dispose the device in compliance with your country's legal and valid regulations for the disposal of electronic and electrical appliances. Correct disposal avoids negative effects on public health and the environment and makes sure recycling of useful raw materials.

This symbol indicates that the directive 2009/96 EG on waste and electronic equipment requirements shall be observed on the disposal of the device.

9. OPERATING PRINCIPLE

9.1. Doppler Flow Meter

An ultrasonic beam is transmitted into the flowing fluid at an oblique angle to the flow. The receiver collects scattered ultrasound from a core group of flowing particles travelling down the central axis of the open channel or pipe. This received ultrasound is shifted in frequency from the transmitted ultrasound in accordance with the general Doppler equation:

$$f_D = 2 * f_0 * \cos(\alpha_0) * \frac{V}{c_0}$$

 f_D is the Doppler shifted frequency

 f_0 is the transmit frequency

V is the average velocity of the scatterers

 c_o is the speed of sound of the fluid

 a_0 is the beam angle relative to the scatterer velocity

The figure below depicts a simplified, two-dimensional diagram of the ultrasound beam injected into the flow stream with the center of the beam at angle. To simplify this explanation, the velocities along the centerline of flow are only considered. If all of the particles along the center flow line travel at the same velocity, there is a distribution of Doppler frequencies corresponding to the change in $\cos(a)$, due to the divergence of the ultrasound beam. The received Doppler shifted frequencies mix with the transmit frequency, resulting in a group of beat frequencies. The time domain, sinusoidal beat signals are digitized and converted to the frequency domain via a fast Fourier transform (FFT). The frequency spectrum generated by the FFT is scanned to find the dominant peak frequency. The point of highest intensity, the frequency spectrum peak, indicates the center flow velocity.

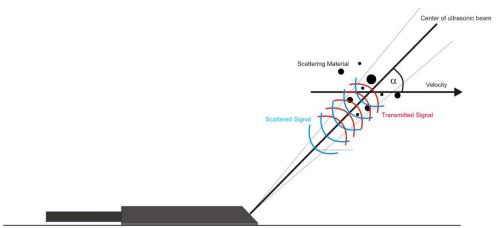


Figure 13: Doppler Principle

Doppler flow meters are not generally promoted for use in clean fluids. In real applications, strong Doppler shifted signals are required for reliable flow measurements.

The amplitude of the Doppler shifted signals from any application is largely related to the suitability of the sonic scatterers in the flow for producing detectable Doppler signals.

Identifying suitable sonic scatterers for Doppler flow meters is a complex combination of four basic criteria. How well the criteria are met determines the reliability and accuracy of a Doppler flow application.

The criteria are:

- The scattering material must have a sonic impedance different from the fluid
- There must be some particles large enough to cause longitudinal scattering
- For a given channel size, the longitudinal scattering must have sufficient energy to overcome the Rayleigh (energy wasting) scattering caused by smaller particles
- The scattering material must travel at the same velocity as the fluid for good accuracy

There are two main types of Doppler flow meter systems in common use today, Continuous Wave and Pulsed Wave. They differ in transducer design and operating features, signal processing procedures and in the types of information provided.

Continuous wave (CW) Doppler is the older and electronically more simple of the two kinds. As the name implies, CW Doppler involves continuous generation of ultrasound waves coupled with continuous ultrasound reception. A two crystal transducer accomplishes this dual function. The main disadvantage of CW Doppler is its lack of selectivity or depth discrimination. CW Doppler measurements are a spot velocity measurement. The sensor is not able to determinate at which level the velocity has been detected. Due to this reason the flow profile cannot be represented. To correct this deficiency, the average flow velocity is computed using a calibration factor. This factor must be determined previously such as by implementing a grid measurement which is time consuming and expensive.

9.2. Pulse Wave Doppler (PW)

Pulsed wave (PW) Doppler systems use a transducer that alternates transmission and reception of ultrasound. One main advantage of pulsed Doppler is its ability to provide Doppler shift data selectively from a small segment along the ultrasound beam, referred to as the "SCAN Window" or cell. The location of the SCAN Window is operator controlled. The ultrasonic pulsed wave Doppler is a new development that supersedes all the older Doppler principles. In contrast to CW Doppler principle, with the Pulse Doppler a shorter ultrasonic frequency bundle of defined length is transmitted. This makes it possible to assign a defined measurement window for received signals, step by step over the entire flow profile. The frequency shift of the transmitted ultrasonic signal into a defined measurement window is the measurement of the flow velocity in that measurement window. Reflections of particles in other areas do not have any influence on the velocity measurement.

9.3. Ultrasonic Signal Diagnostics

The flow information is derived from ultrasonic signals travelling through a moving fluid. One of the most critical aspects of the ultrasonic flow meter diagnostic software is to evaluate the individual ultrasonic signals to determine if the signal is acceptable for an accurate velocity measurement. If there is a problem with the ultrasonic signals themselves, the flow measurement will be incorrect. It is impossible to state what an ultrasonic signal should look like in general, but essentially the signal needs to appear as expected by the receiver and processing software.

The amplitude or strength of the ultrasonic signal (dB) depends on just about every aspect of the measurement system. Depending on the distance of the SCAN Window from the sensor, the lower is the received signal because of spreading and signal scattering within the fluid. High suspended loads weaken the signal as well.

In general, signal strength readings between 50 dB and 80 dB are expected with a properly mounted sensor. Signal strength readings higher than 90 dB may indicate that the sensor need to be cleaned, as dirt may weaken the signal or sediment covers the sensor. Signal strengths lower than 35 dB are considered to be no signal at all.

10. TECHNICAL DATA

10.1. Transmitter

Display	LC-Display, 4 lines, 20 characters			
Keyboard	4 keys			
Enclosure	IP 66; Aluminum;			
Enclosure	wall mounted indoor use only or environmental enclosure			
Operating	4 140° F / 20 C0° C			
Temperature	-4140° F (-2060° C)			
Storage Temperature	-4158° F (-2070° C)			
Maximum Humidity	90% (non-condensing)			
Maximum Operating	AC device: 2000 m above sea level			
Altitude	AC device: 2000 iii above sea ievei			
Power Supply	100240V AC, ±10% 4763Hz or 1036V DC, ±15%, 5% residual ripple			
Dower Consumption	AC: max. 40 VA, typically: 30VA			
Power Consumption	DC: max. 30 W, typically: 8 W			
Onevating	Protection class I			
Operating Conditions	Overvoltage category I			
Conditions	Pollution degree 2			
Outputs Analog	our 420 mA active channels, load <550 Ohms			
Outputs Digital	Four relays 60V DC 1A or 30V AC 1A 200 Hz max.; normally open or normally closed			
Outputs Digital	Two pulse/frequency outputs; 24V DC			
Inputs Analog	Four 420 mA input channels; 1 channel reserved for level			
Inputs Digital	Two inputs 30V DC max.			
Communication	Modbus RTU 485; Modbus TCP Ethernet 10/100 Mbps RJ45			
Programming Port	Webserver using standard web browser via WiFi or Ethernet;			
Programming Port	English, French, German, Spanish, Polish, Czech, Russian or Japanese languages			
Data Logging	16 GB Micro SD card; 12 months of storage; file transfer through web browser			
Channel/Pipe Shapes	Round radius, U-shape, rectangular, trapezoid, egg-shape, custom channel			
CE Compliance	Low Voltage Directive, 2014/35/EU, EMC 2014/30/EU, Radio Equipment Directive 2014/53/EU,			
CE Compnance	RoHS 2 2011/65/EU, 2015/863/EU			
Contification Ontion	cCSAus general area indoor use: CAN/CSA-C22.2 No. 61010-1-12, UPD1:2015, UPD2:2016,			
Certification Option	AMD1:2018; UL 61010-1 Third Edition (2012), AMD1:2018			

10.2. Area Velocity Sensor



Sensor	Integrated Doppler ultrasonic velocity and water level with temperature measurement
Measuring Principle	Velocity: pulse coherent
Water level	Ultrasonic travel time
water ievei	Medium Wastewater ≥ 50 ppm
Frequency	1 MHz
Beam Angle	45°
Number of Cells	Max. 32 cells
Operating Temperature	5122° F (-1550° C)
	Velocity: ± 16.5 ft/s (± 5.0 m/s)
Velocity Range	Min. detectable flow velocity \pm 0.13 ft/s (\pm 0.04 m/s) depending on size and amount of
	particles
	± 1% full scale in the range 5.016.5 ft/s and -5.016.5 ft/s
Volosity Assurasy	(1.55.0 m/s and -5.01.5 m/s)
Velocity Accuracy	±0.1 ft/s in the range -5.05.0 ft/s
	(± 0.03 m/s in the range -1.51.5 m/s)
Water Level Range	1.651 in. (0.041.3 m)
water Level halige	Expandable via external 420 mA sensor
Water Level Accuracy	± 2.6 in. (± 0.065 m)
	± 0.5 K for 457°C;
Temperature Accuracy	Linearized range: 060° C
	Overall range: -60150° C
Flow Accuracy	Typically ± 2% of reading
Material	Stainless steel (main unit, base plate)
iviatei iai	PEEK (Piezo Oscillator cover lid)
Protection Class	IP 68
	7.1 x 1.6 x 0.9 in. (LxWxH)
Dimensions	180 x 40 x 22 mm (LxWxH)
	(incl. base / mounting plate)
Cable Length	32262 ft (1080 m)
Cable Outer Jacket	Polyethylene; Diameter Ø 0.4 ± 0.012 inn $(10.00 \pm 0.3 \text{ mm})$
Cable Operating Temperature	-4158° F (-2070° C)
Range	7150 1 (2070 C)

11. ANNEX

11.1. Roughness Coefficients

Manning's equation roughness coefficients for various channel materials

The Manning's equation is an empirical formula for open channel flow.

Function of velocity, flow area, channel slope and roughness

Q=vA with $V=k_{_{S_{t}}}\,Rh^{~2/3}$ Ic $^{^{1\!/_{\!\!2}}}$

Q: Discharge

v: Flow velocity

k_s: Roughness coefficient (Strickler)

R_k ^{2/3}: Hydraulic radius (cross sectional A / wetted perimeter P)

I 22: Channel downward slope

Empirical roughness coefficients are listed in sets of tables (see below). The following symbols are used:

k_s, = Strickler coefficient (more known in Europe)

n = Manning Coefficient

 $k_{ct}[m^{1/3}/s] = 1/n$

NOTE: Information in the following tables was taken from Isco Open Channel Flow Measurement Handbook & *CeCalc.com - Civil Engineering Calculations [2]

11.1.1. Closed conduit, Partly Full Metal Pipes

	Material	٨	Manning Coeff.		
		n min	n Norm	n max	kst
1. Steel	a. Lockbar and welded	0.010	0.012	0.014	83
	b. Riveted and spiral	0.013	0.016	0.017	63
2. Cast Iron	a. Coated	0.010	0.013	0.014	77
	b. Uncoated	0.011	0.014	0.016	71
3. Wrought Iron	a. Black	0.012	0.014	0.015	71
	b. Galvanized		_		_
4. Corrugated	a. Subdrain	0.017	0.019	0.021	53
	b. Storm Drain	0.021	0.024	0.030	42

Table 2: Specific roughness coefficients (Manning & Strickler coefficients) for closed conduit, partly full metal pipesl

11.1.2. Closed Conduit, Partly Full Non-Metal Pipes

Material		Manning Coeff.			Strickler Coeff.
		n min	n Norm	n max	kst
1. Synthetics/ plastics	a. Acrylic	0.008	0.009	0.010	111
	b. Polyethylene (PE)	0.008	0.009	0.011	111
	c. Corrugated Polyethylene Culvert Pipe (smooth)	0.009	0.013	0.015	77
	d. Corrugated Polyethylene Culvert Pipe (corrugated)	0.018	0.023	0.025	43
	e. Polyvinyl chloride (PVC)	0.009	0.010	0.011	100
2. Glass	_	0.009	0.010	0.013	100
3. Wood	a. Stave	0.010	0.012	0.014	83
	b. Laminated, treated	0.015	0.017	0.020	59
4. Clay	a. Common drainage tile	0.011	0.013	0.017	77
	b. Vitrified sewer	0.011	0.014	0.017	71
	c. Vitrified sewer with manholes, inlets, etc.	0.013	0.015	0.017	67
5. Brick	a. Glazed	0.011	0.013	0.015	77
	b. Lined with cement	0.012	0.015	0.017	67
6. Concrete	a. Culvert, straight and free of debris	0.010	0.011	0.013	100
	b. Culvert with bends, connections and some debris	0.011	0.013	0.017	77
	c. Sewer with manholes, inlet, etc., straight	0.013	0.015	0.017	67
	d. Unfinished, steel form	0.012	0.013	0.014	83
	e. Unfinished, smooth wood form	0.012	0.014	0.016	83
	f. Unfinished, rough wood form	0.015	0.017	0.020	59
7. Sanitary sewers coated with sewage slimes		0.012	0.013	0.016	77
8. Paved invert, sewer,	smooth bottom	0.016	0.019	0.020	53
9. Rubble masonry, ce	mented	0.018	0.025	0.030	40

Table 3: Specific roughness coefficients (Manning & Strickler coefficients) for closed conduit, partly full non-metal pipesl

11.1.3. Lined or Built-Up Metal Channels

Material		М	anning Coe	ff.	Strickler Coeff.
		n min	n Norm	n max	kst
1. Smooth steel surface	a. Painted	0.011	0.012	0.014	83
	b. Unpainted	0.012	0.013	0.017	77
2. Corrugated	_	0.021	0.025	0.030	40

 $\textit{Table 4: Specific roughness coefficients (Manning \& Strickler coefficients) for lined or built-up \ metal\ channels}$

11.1.4. Lined or Built-Up Non-Metal Channels

Material		N	Manning Coeff.		
		n min	n Norm	n max	kst
1. Cement	a. Neat surface	0.010	0.011	0.013	91
	b. Mortar	0.011	0.013	0.015	77
2. Concrete	a. Trowel finish	0.011	0.013	0.015	77
	b. Float finish	0.013	0.015	0.016	67
	c. Finished, with gravel on bottom	0.013	0.017	0.020	59
	d. Unfinished	0.014	0.017	0.020	59
3. Wood	a. Planed, untreated	0.0.1	0.012	0.014	83
	b. Planed, creosoted	0.011	0.012	0.015	83
	c. Unplaned	0.011	0.013	0.015	77
	d. Plank with battens	0.012	0.015	0.018	67
	a. Glazed	0.011	0.013	0.015	77
	b. In cement mortar	0.012	0.015	0.018	67
5. Masonry	a. Cemented rubble	0.017	0.025	0.030	40
	b. Dry rubble	0.023	0.032	0.035	31
6. Asphalt	a. Smooth	0.013	0.013	_	77
	b. Rough	0.016	0.016		63
7. Vegetal lining		0.030	_	0.500	_

Table 5: Specific roughness coefficients (Manning & Strickler coefficients) for lined or built-up non-metal channels

11.1.5. Excavated or Dredged Channels

Material		Manning Coeff.			
		n Norm	n max	kst	
A. Earth, straight and uniform	0.016	0.022	0.035	29	
B. Earth, winding and sluggish	0.023	0.030	0.040	25	
C. Rock cuts	0.030	0.040	0.040	25	
D. Unmaintained channels	0.040	0.070	0.140	7	

Table 6: Specific roughness coefficients (Manning & Strickler coefficients) for excavated or dredged channels

11.1.6. Natural Channels

Material		Manning Coeff.		
	n min	n Norm	n max	kst
A. Fairly regular section	0.030	0.050	0.070	20
B. Irregular section with pools	0.040	0.070	0.100	14

Table 7: Specific roughness coefficients (Manning & Strickler coefficients) for regular/irregular sections

11.2. Bibliography

- [1] DIN 4263 (2011): Kennzahlen von Abwasserkanälen und -leitungen für die hydraulische Berechnung im Wasserwesen, Beuth Verlag GmbH, Berlin, 9 S.
- [2] ISO 748:2007: Hydrometry Measurement of liquid flow in open channels using current-meters or floats (ISO 748:2007); German version EN ISO 748:2007.
- [3] Grant, Douglas M., Dawson, Brian D. (2001): Isco Open Channel Flow Measurement Handbook, 5 th edition; Isco Inc. Lincoln, Nebraska, USA.

